

# Vehicle-Track Measurement Technologies

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ENSCO Rail

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# Summary

**Overview of Measurement Systems**

**Overview of Asset Management**

**The Future is Here**



# Overview of Measurement Systems

*There are five basic categories of measurement system.*



# Categories of Measurement Systems

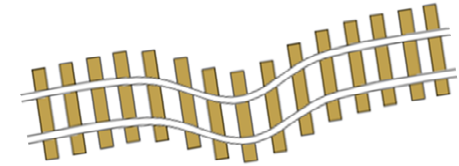
1) Mounted on Vehicle to measure the Vehicle.





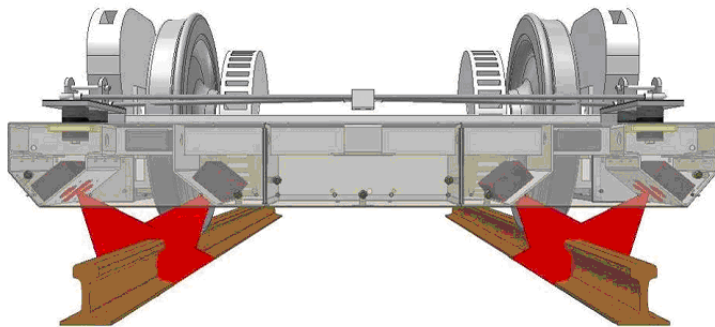
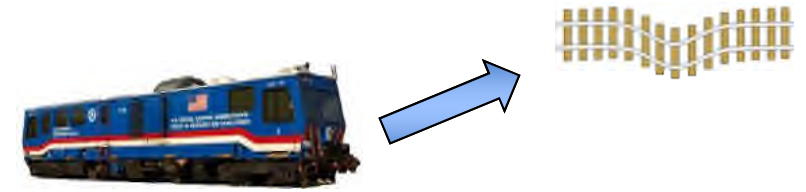
# Categories of Measurement Systems

2) Mounted on Track to measure the Track.



# Categories of Measurement Systems

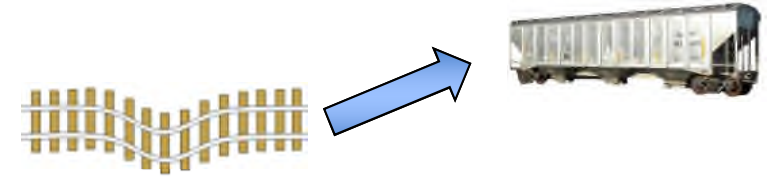
3) Mounted on Vehicle to measure the Track.  
(Manned, Unmanned, and Autonomous)





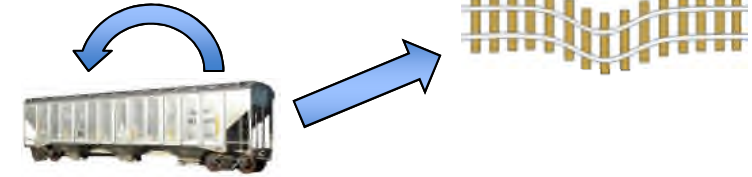
# Categories of Measurement Systems

4) Mounted on Track to measure the Vehicle.



# Categories of Measurement Systems

5) Mounted on Vehicle to measure the Vehicle & Track.



## Track Measurement

**Rail Profile Measurement System**

**Track Geometry Measurement**

**V/TI Monitor Axle Impact**

**Ultrasonic Rail Flaw Detector**

**Machine Vision**



## Vehicle Measurement

**Wheel Profile Detector**

**Truck Condition Monitor  
(TBOGI)**

**Wheel Impact Load Detector**

**Cracked Wheel Detector**

**Machine Vision**

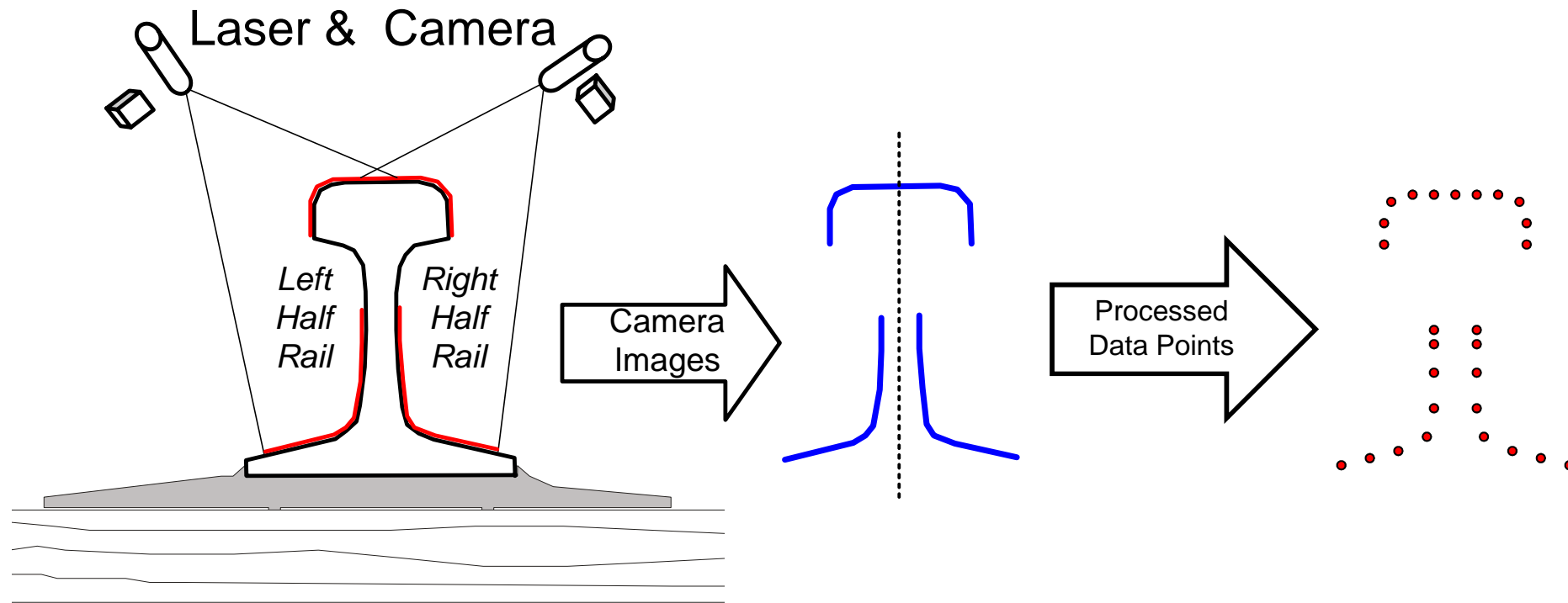




# Profile Measurement



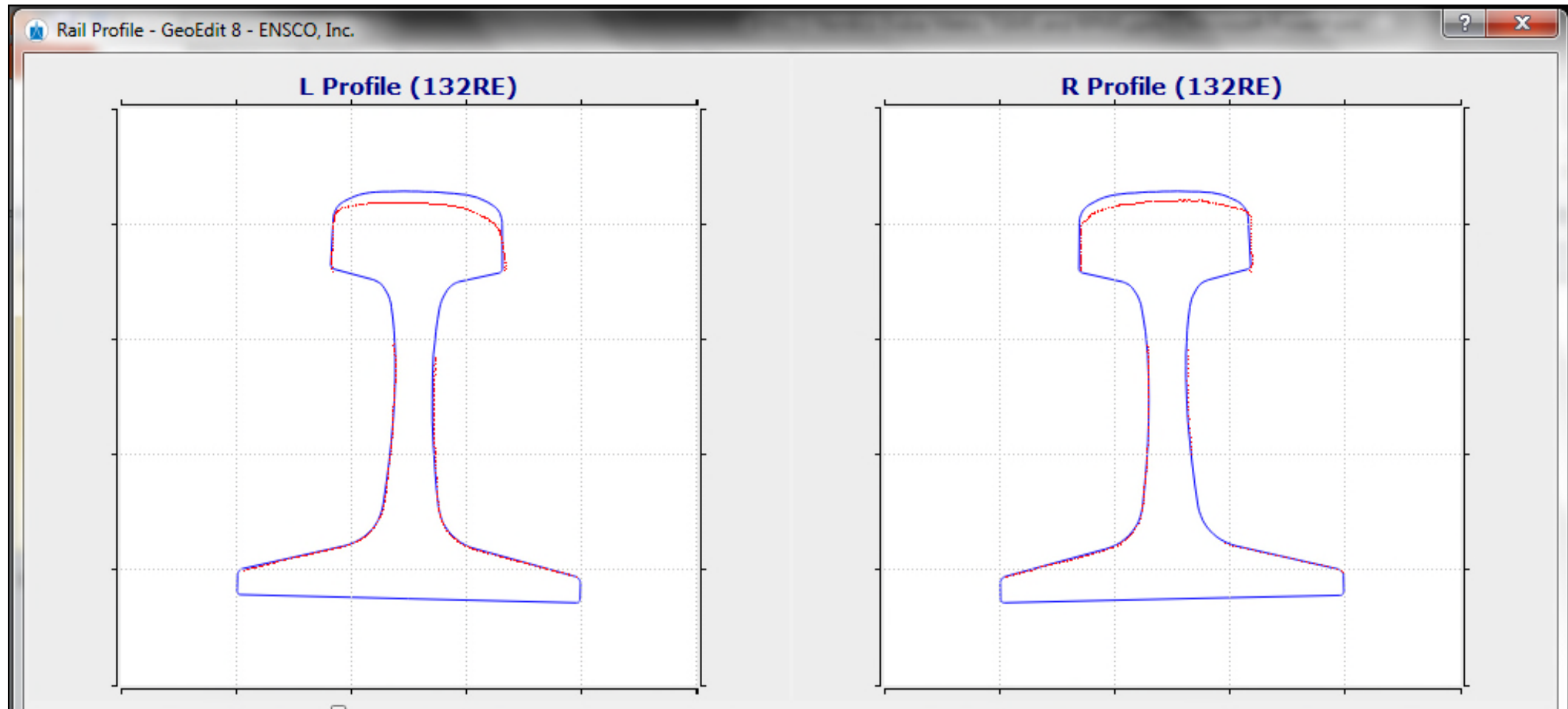
# Laser Triangulation Measurement



Ref 1

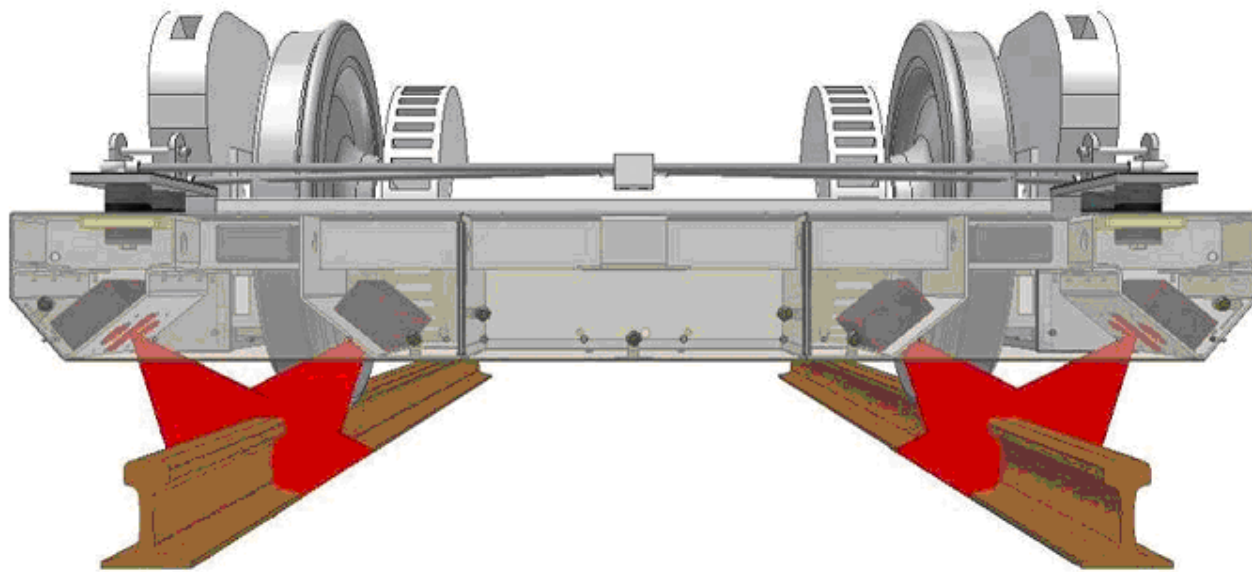


# Laser Triangulation Measurement





# Rail Profile Measurement System



# Vehicle Platforms:



Railbound Manned



Hi-Rail Manned



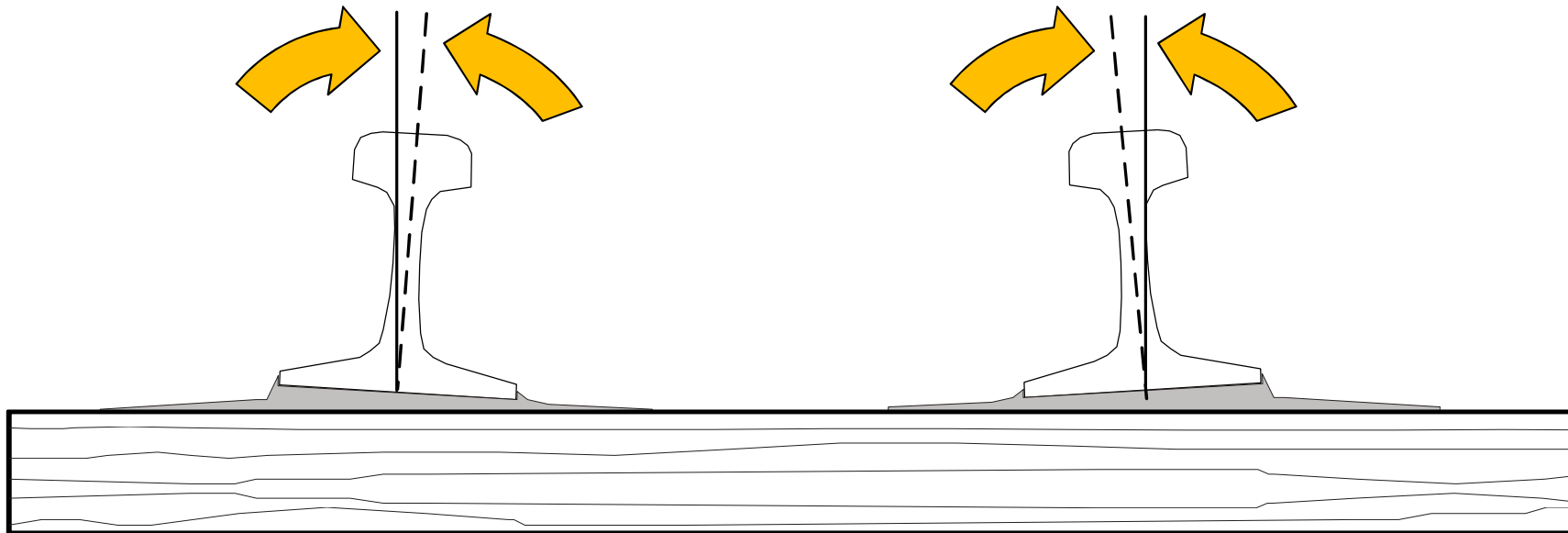
Autonomous



# Absolute Measurements:

(Doesn't Require Template)

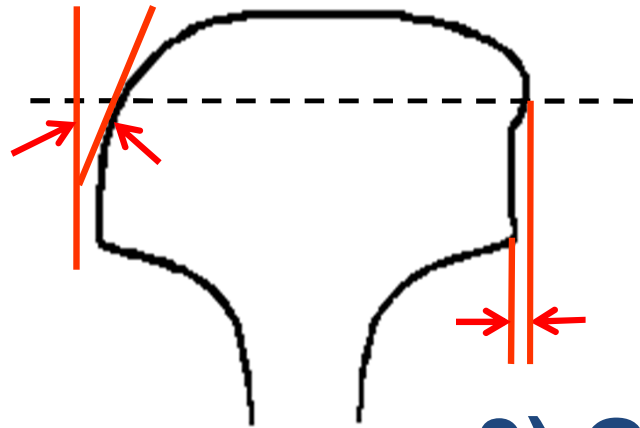
## 1) Cant (Deg)



# Absolute Measurements:

(Doesn't Require Template)

**2) Gage  
Face Angle  
(Deg)**



**3) Gage/Field  
Side Lip (In, mm)**

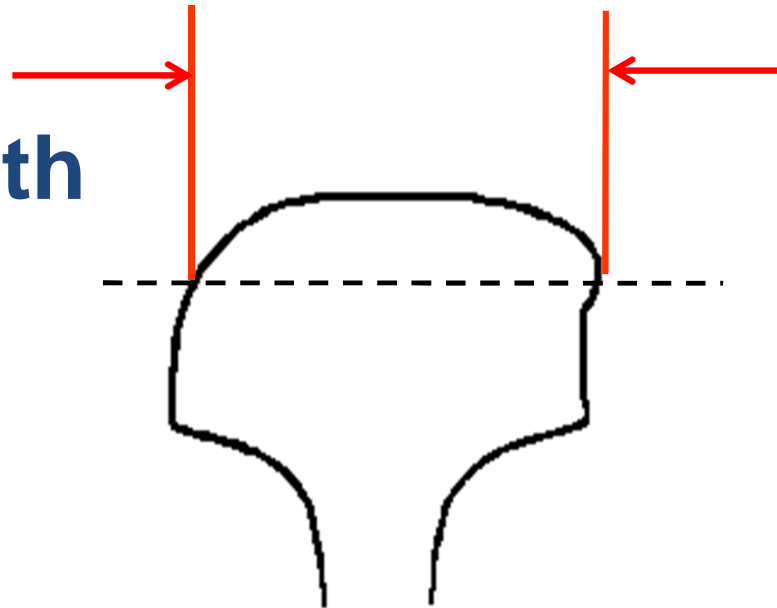




# Absolute Measurements:

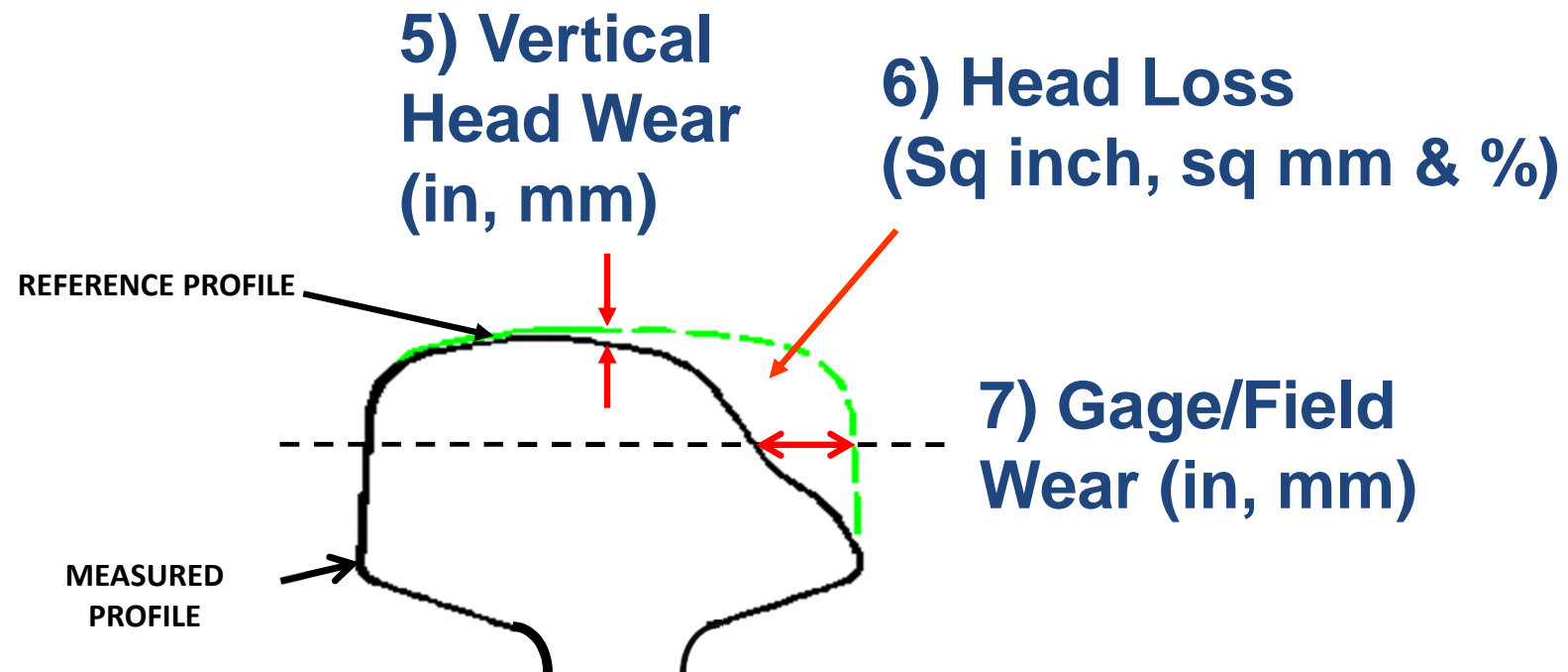
(Doesn't Require Template)

**4) Head Width  
(in, mm)**



# Relative Measurements:

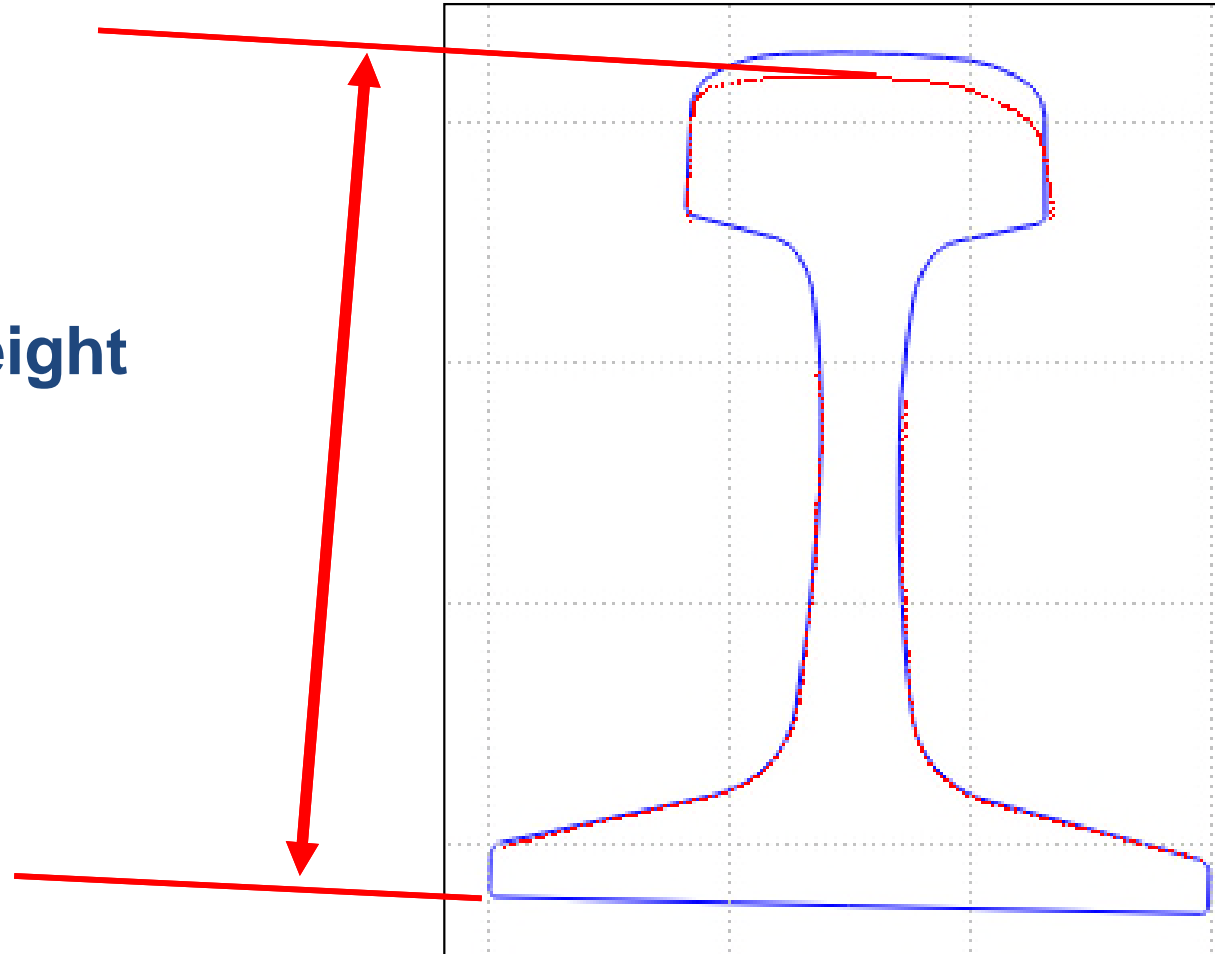
(Does Require Template)

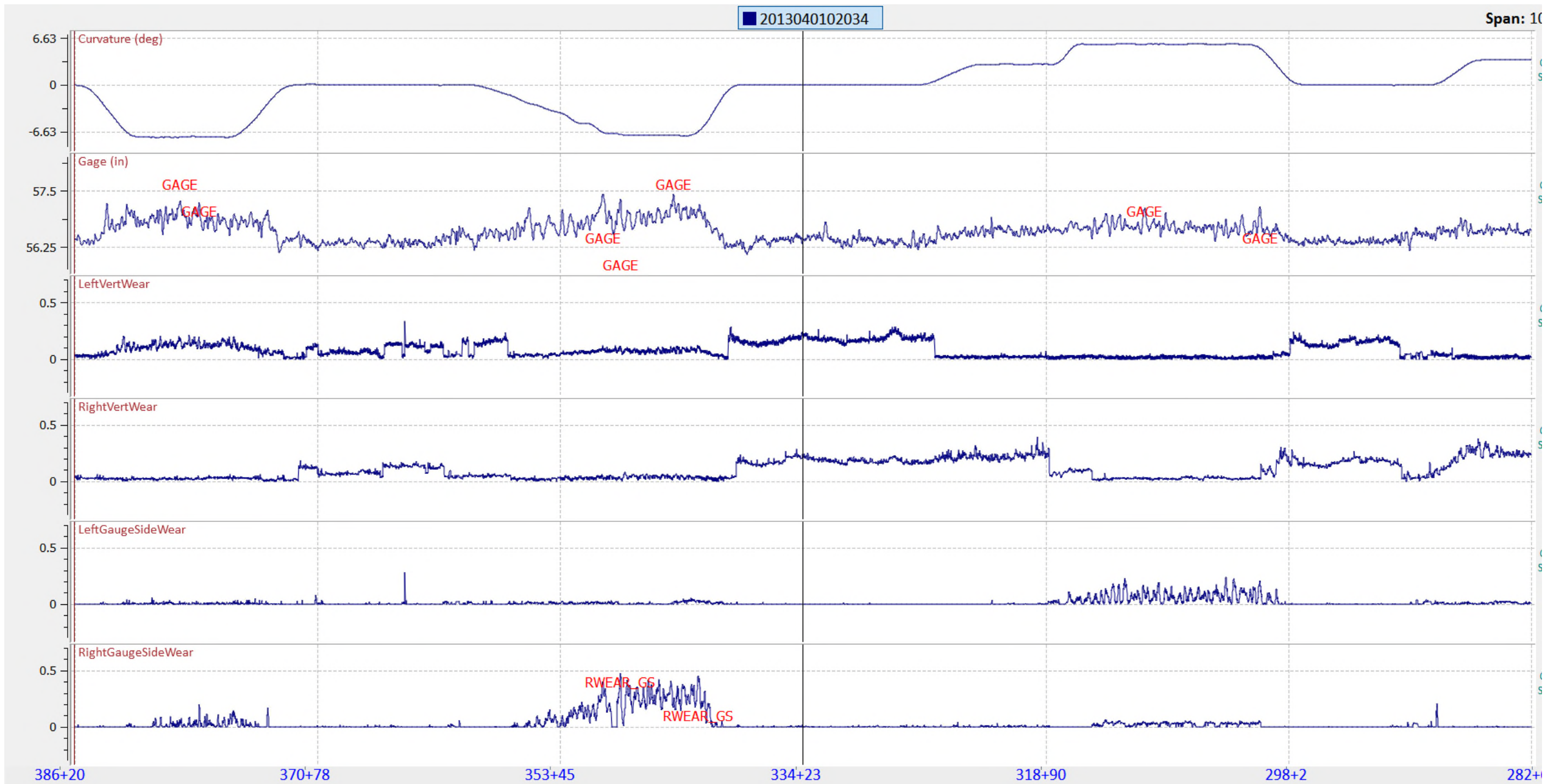


# Relative Measurements:

(Does Require Template)

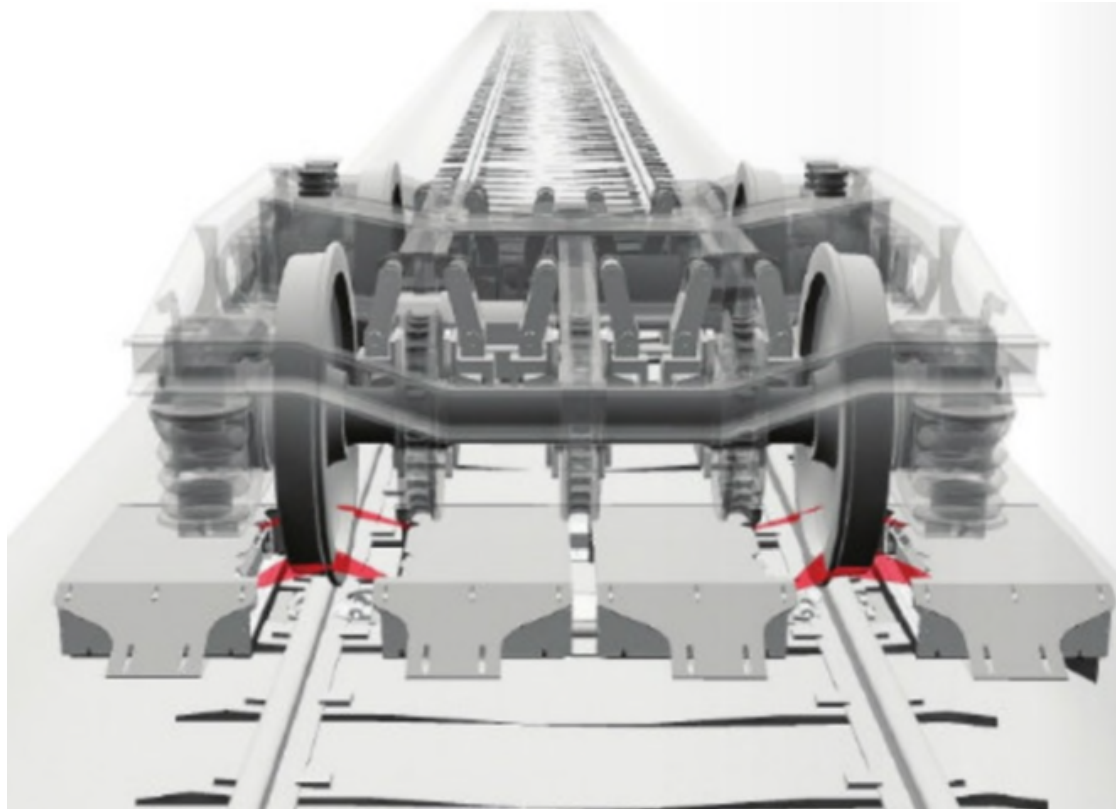
**8) Total Height  
(in, mm)**





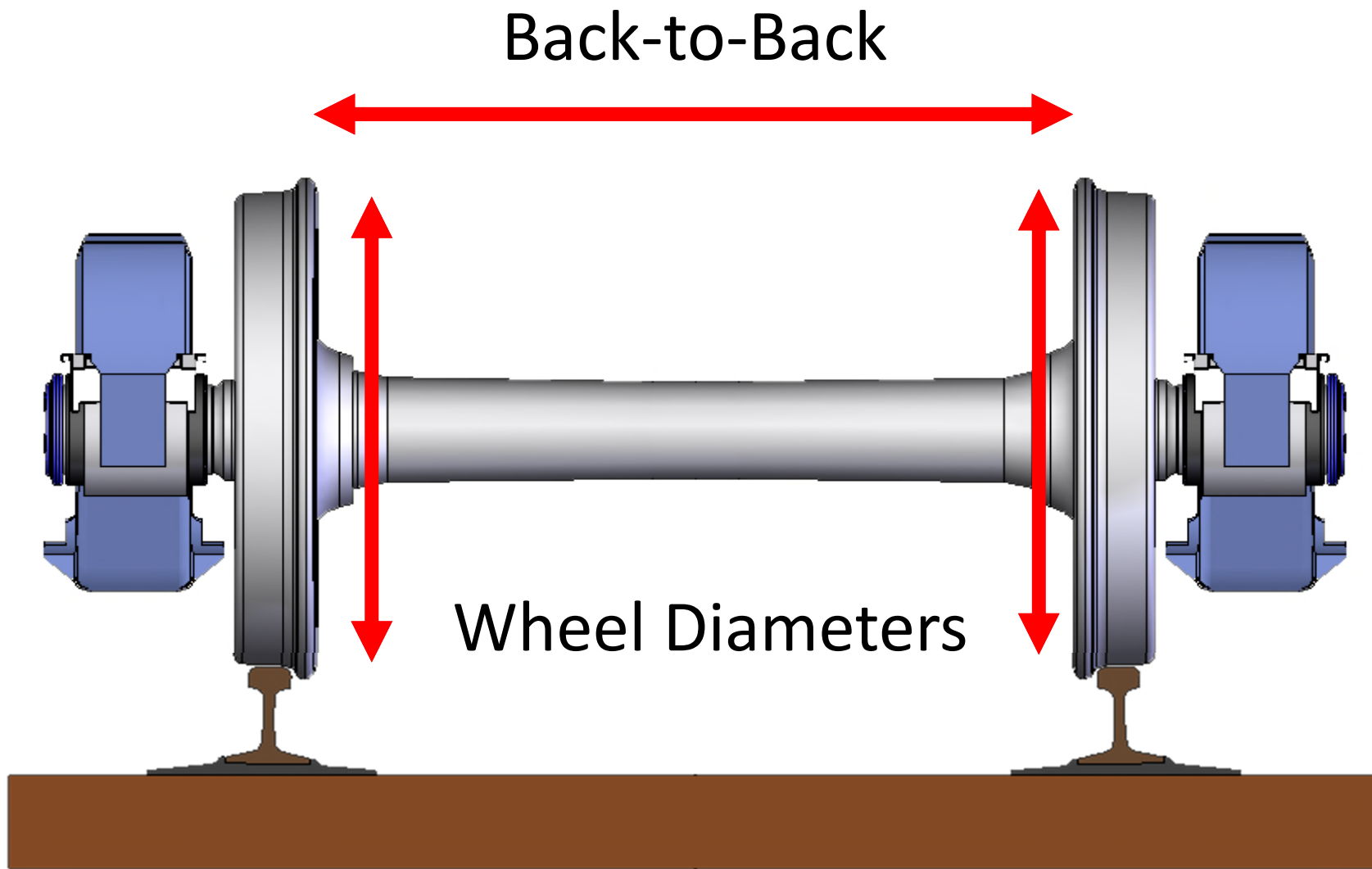


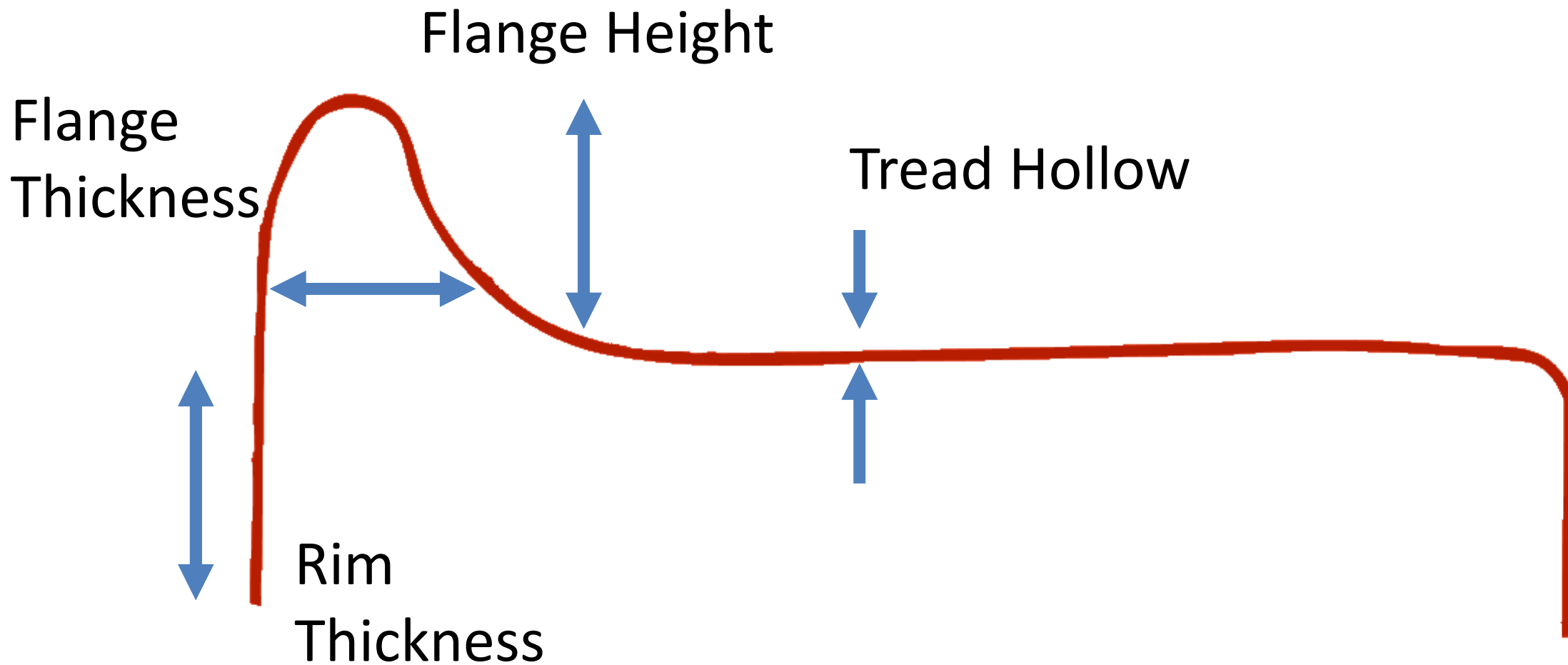
# Wheel Profile Detector



Images from Beena Vision  
[http://www.beenavision.com/BV\\_Brochure\\_2016/mobile/index.html#p=16](http://www.beenavision.com/BV_Brochure_2016/mobile/index.html#p=16)







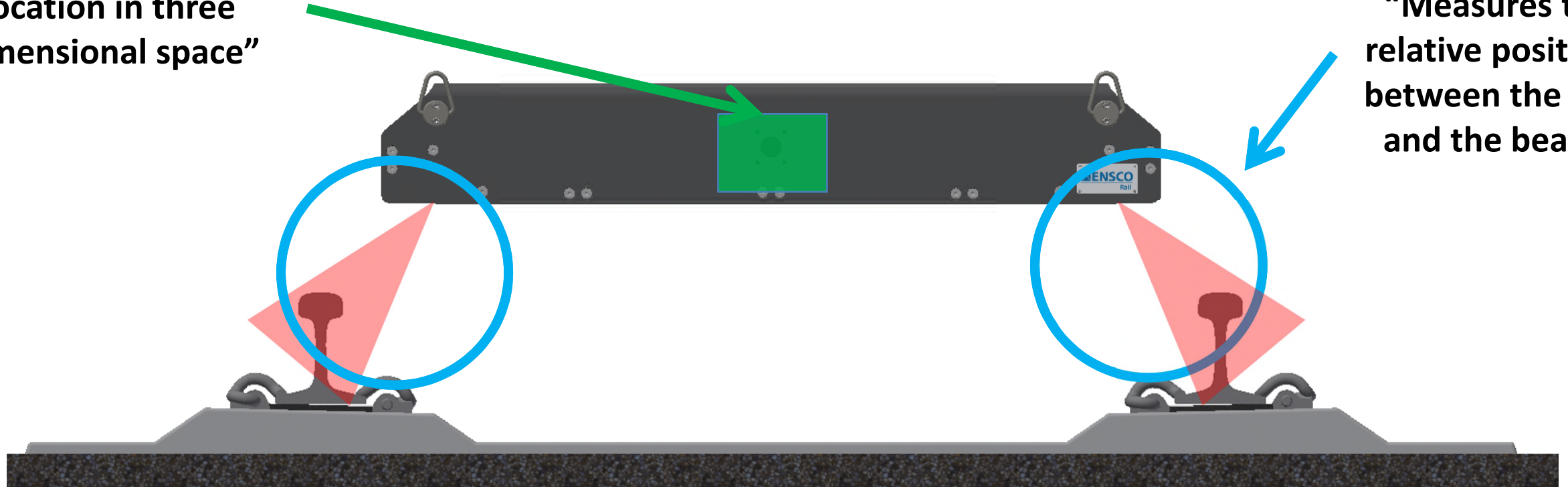
# Geometry Measurement



# Track Geometry Measurement System

**Inertial Package**  
“Measures the beam location in three dimensional space”

**Laser/Cameras**  
“Measures the relative positions between the rails and the beam”





# Vehicle Platforms:



Railbound Manned



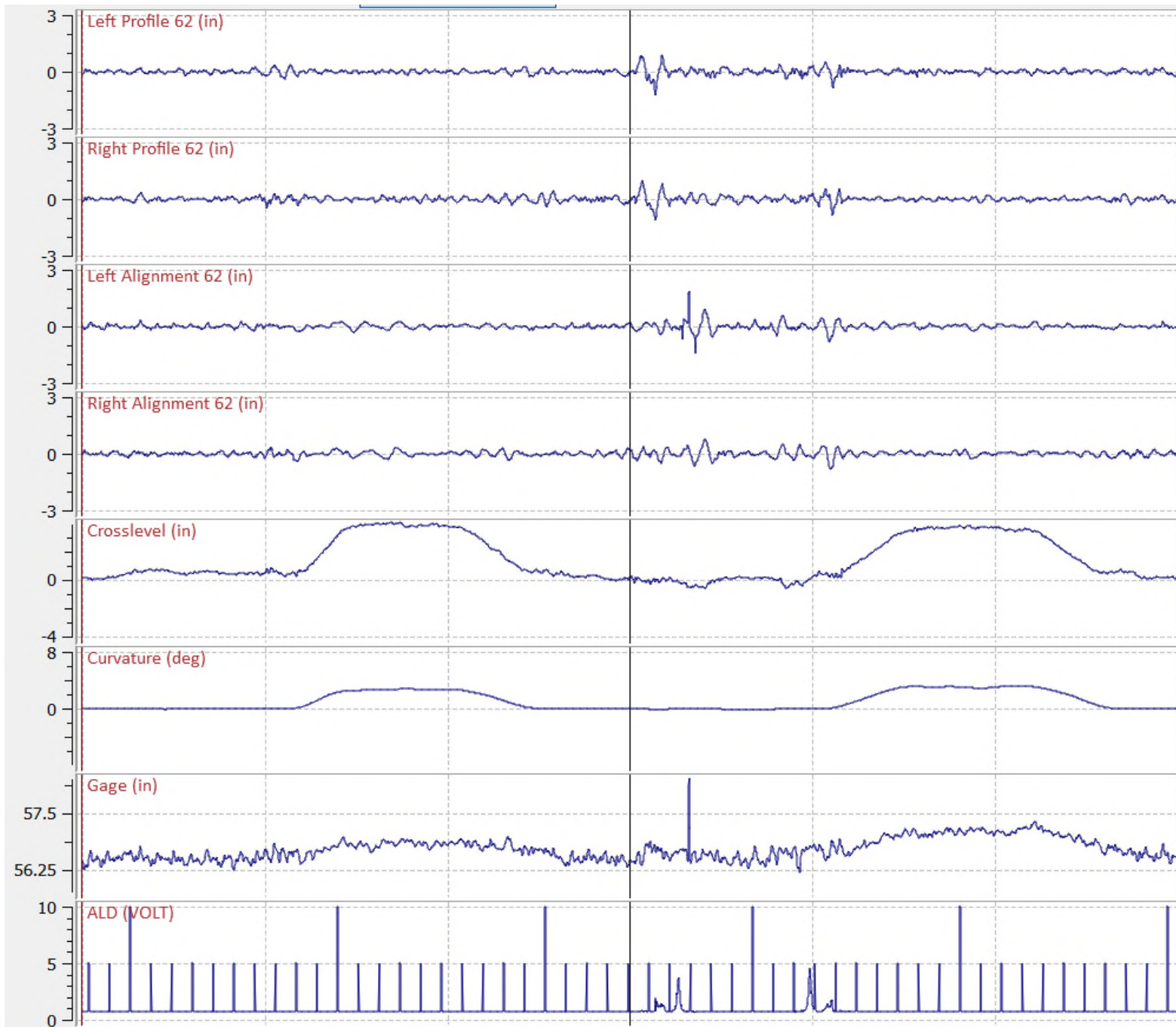
Hi-Rail Manned



Autonomous

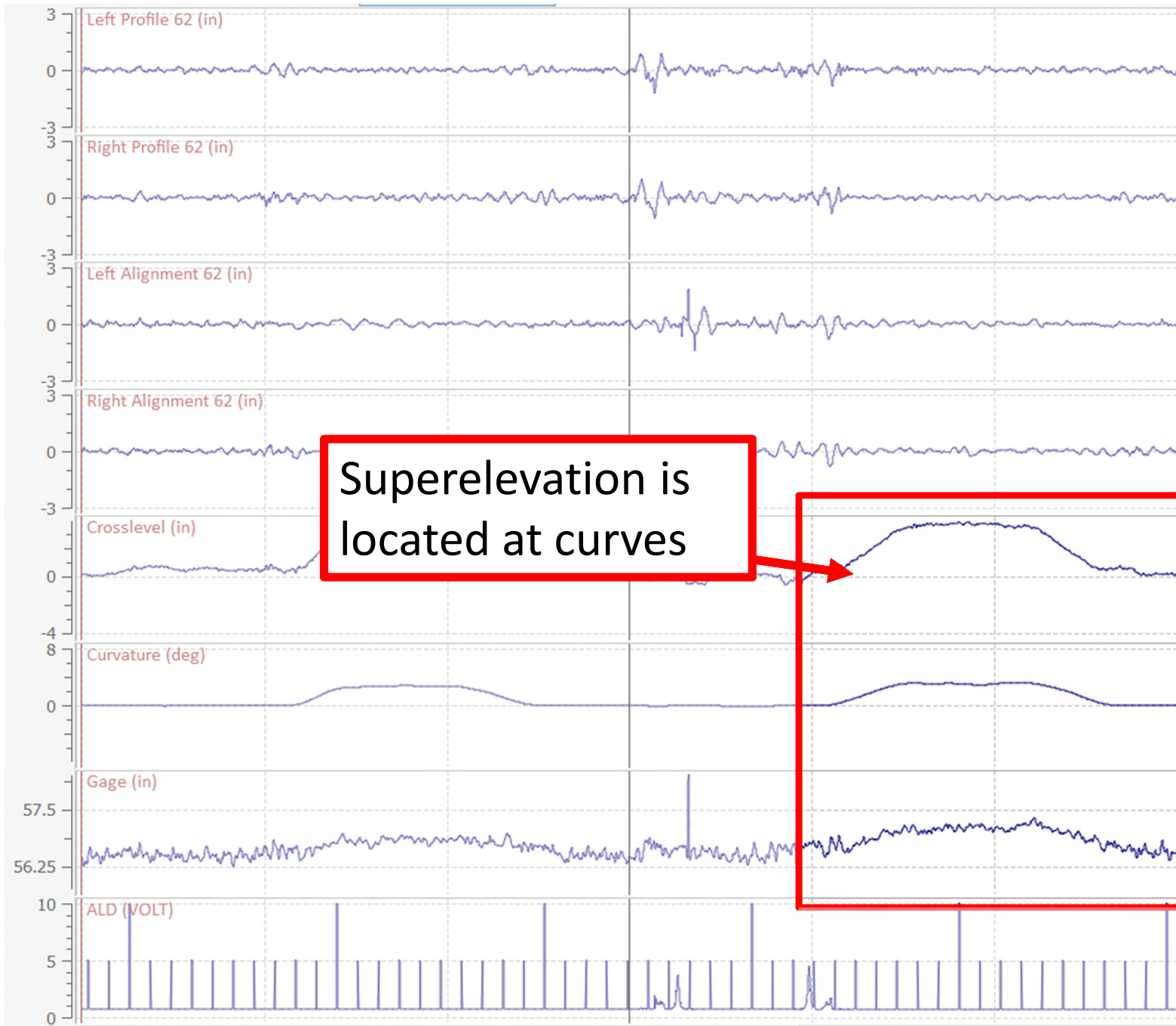


# Example Track Geometry Strip Chart



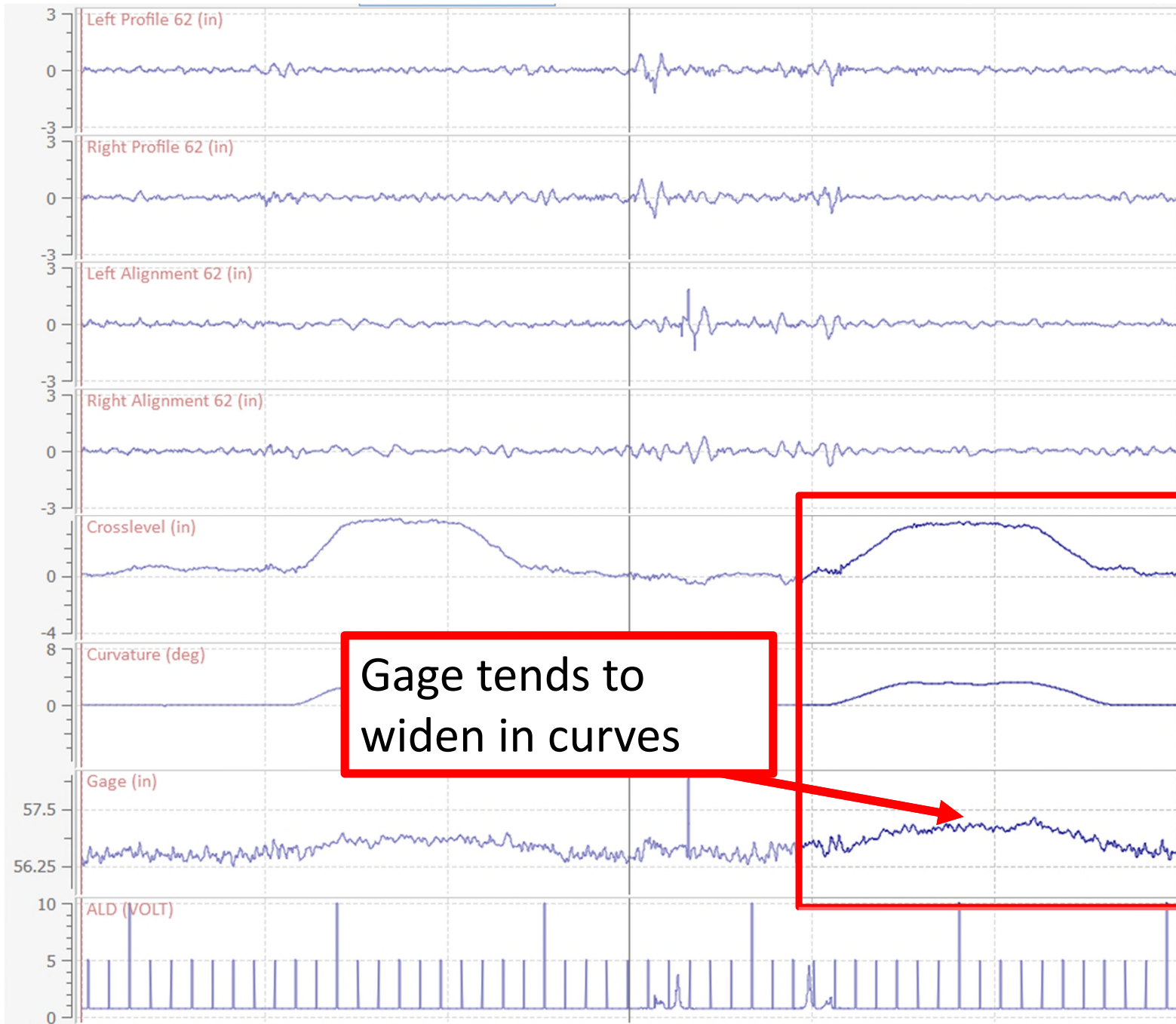


# Example Track Geometry Strip Chart

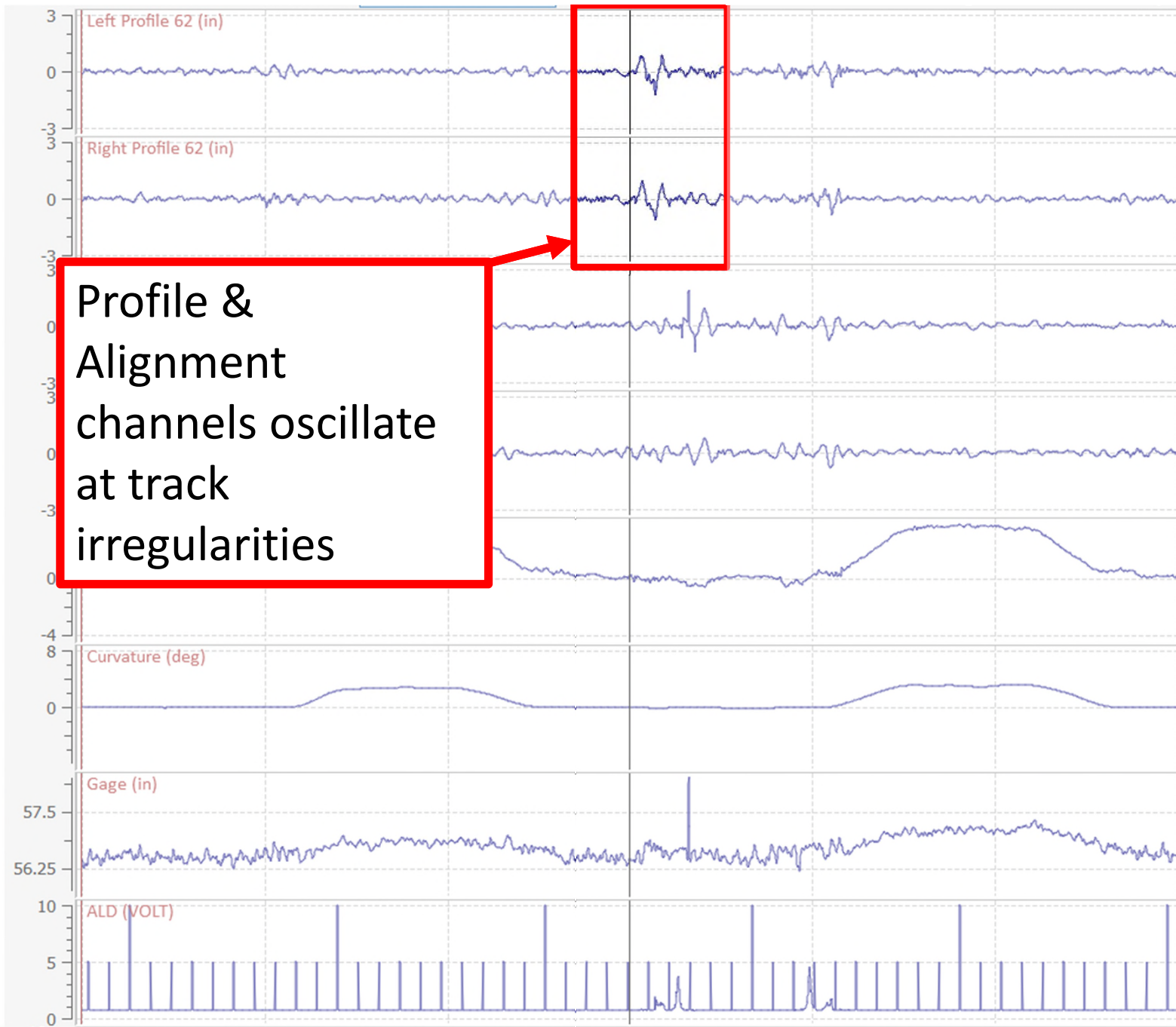




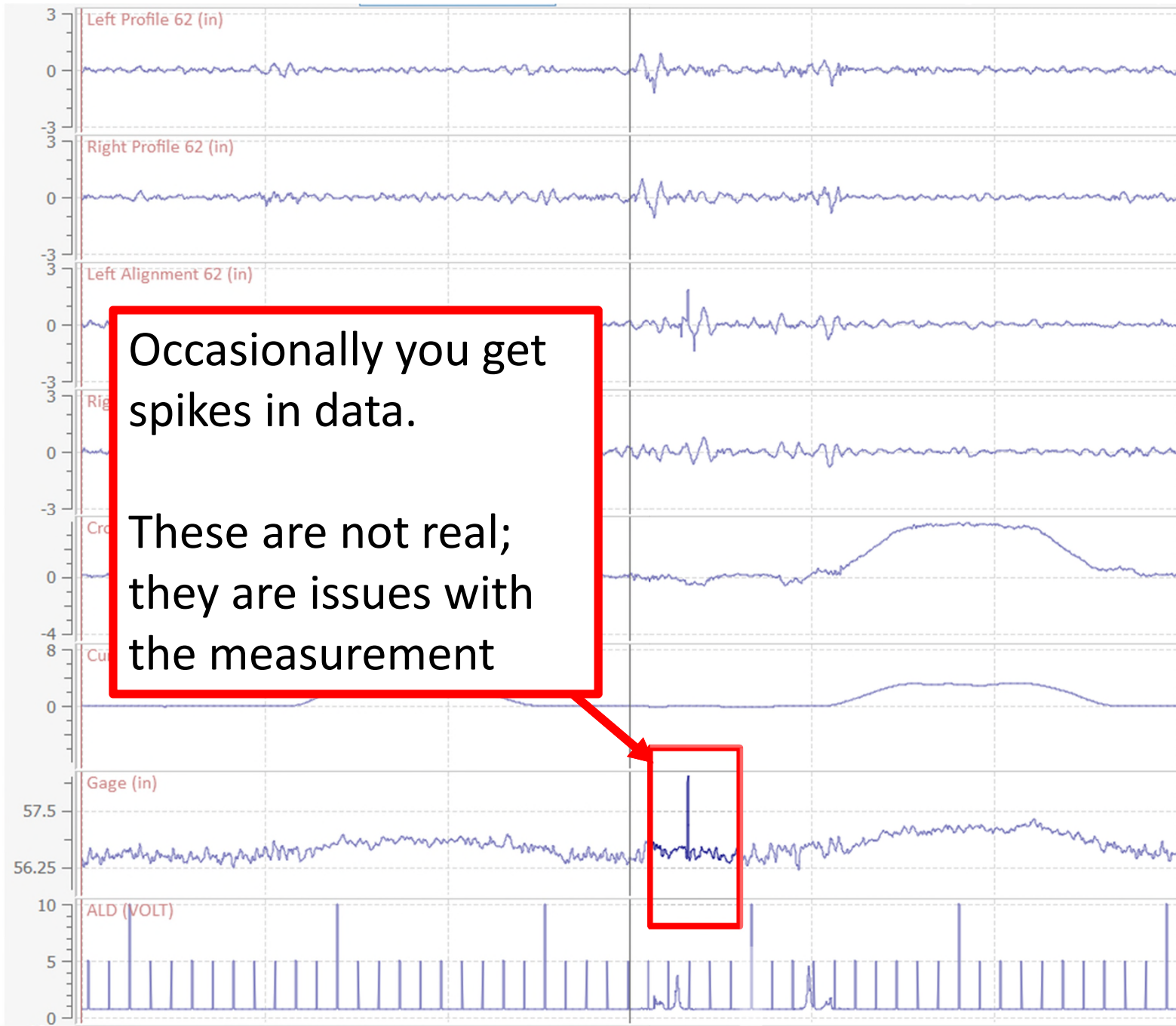
# Example Track Geometry Strip Chart



**Example  
Track  
Geometry  
Strip Chart**

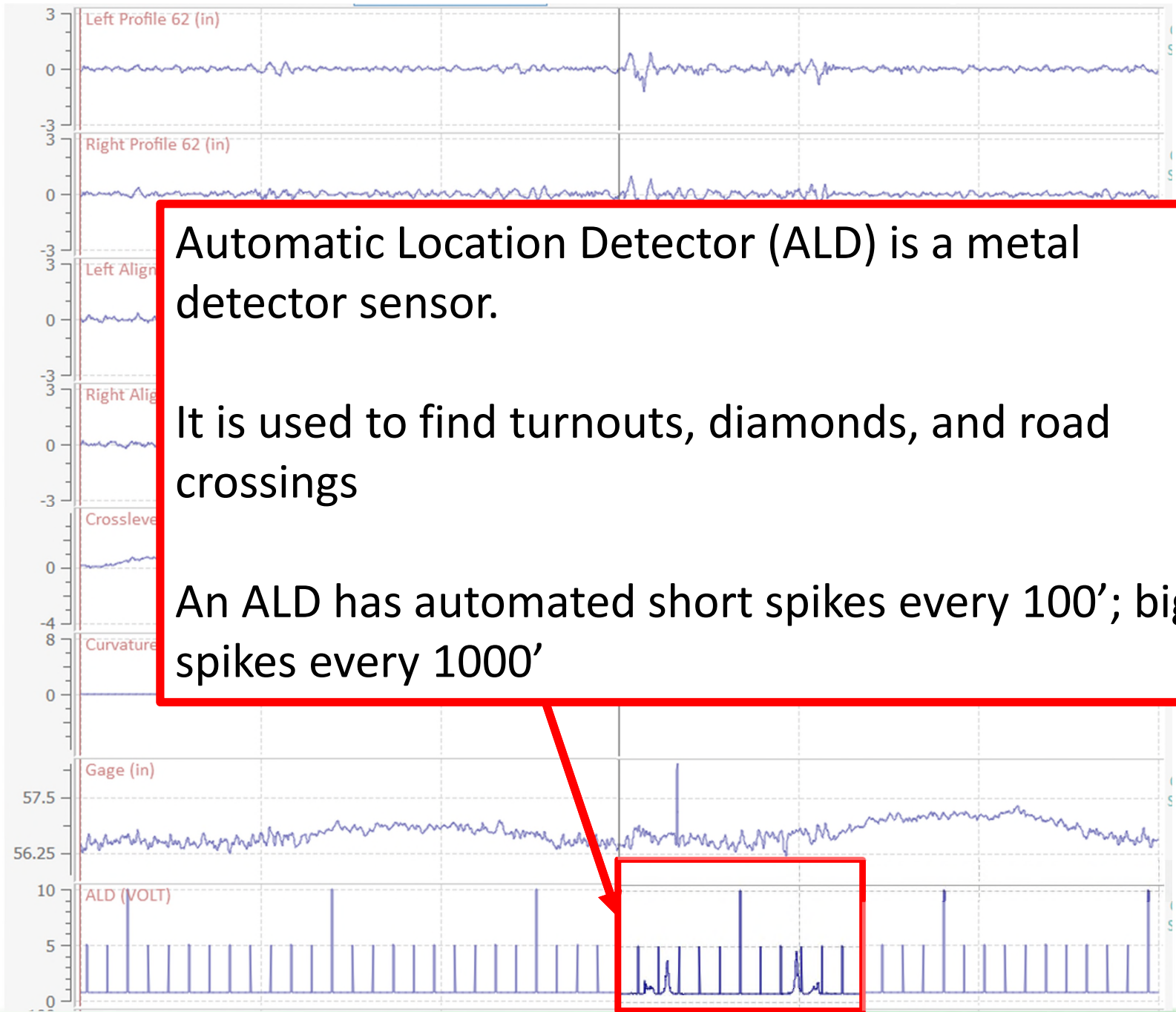


# Example Track Geometry Strip Chart





**Example  
Track  
Geometry  
Strip Chart**



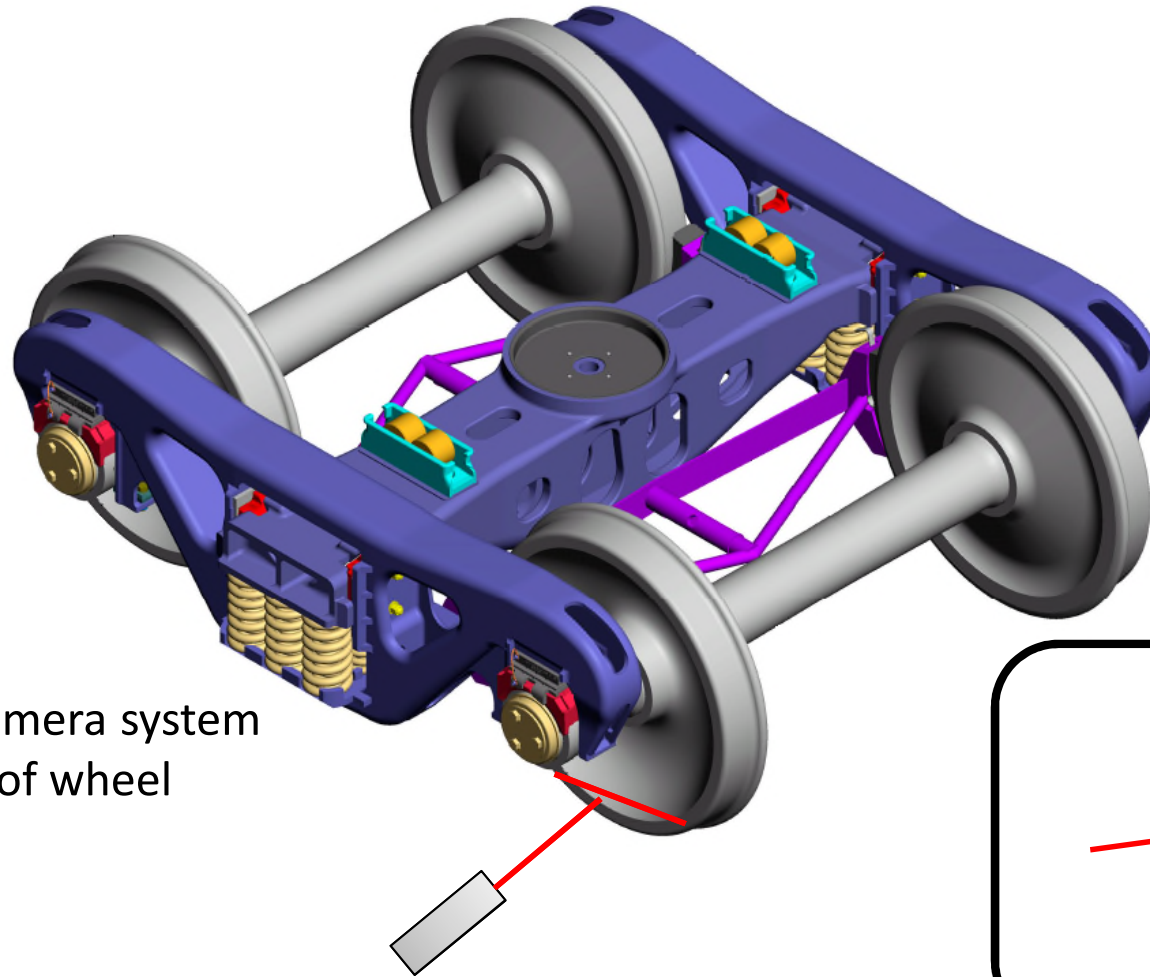
Automatic Location Detector (ALD) is a metal detector sensor.

It is used to find turnouts, diamonds, and road crossings

An ALD has automated short spikes every 100'; big spikes every 1000'



# Truck Condition Monitor (T-BOGI)



Wayside Laser/Camera system measures profile of wheel plate.

Laser

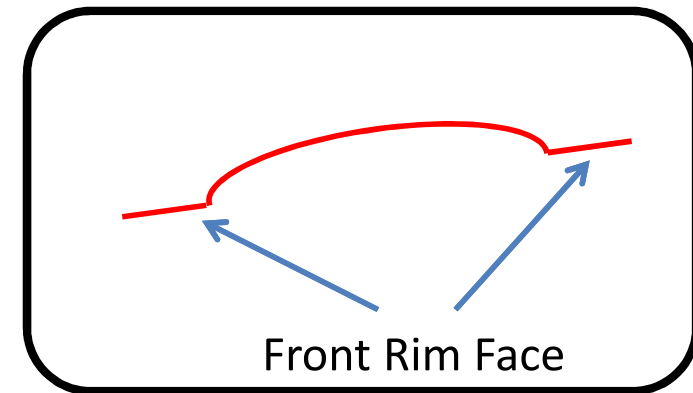
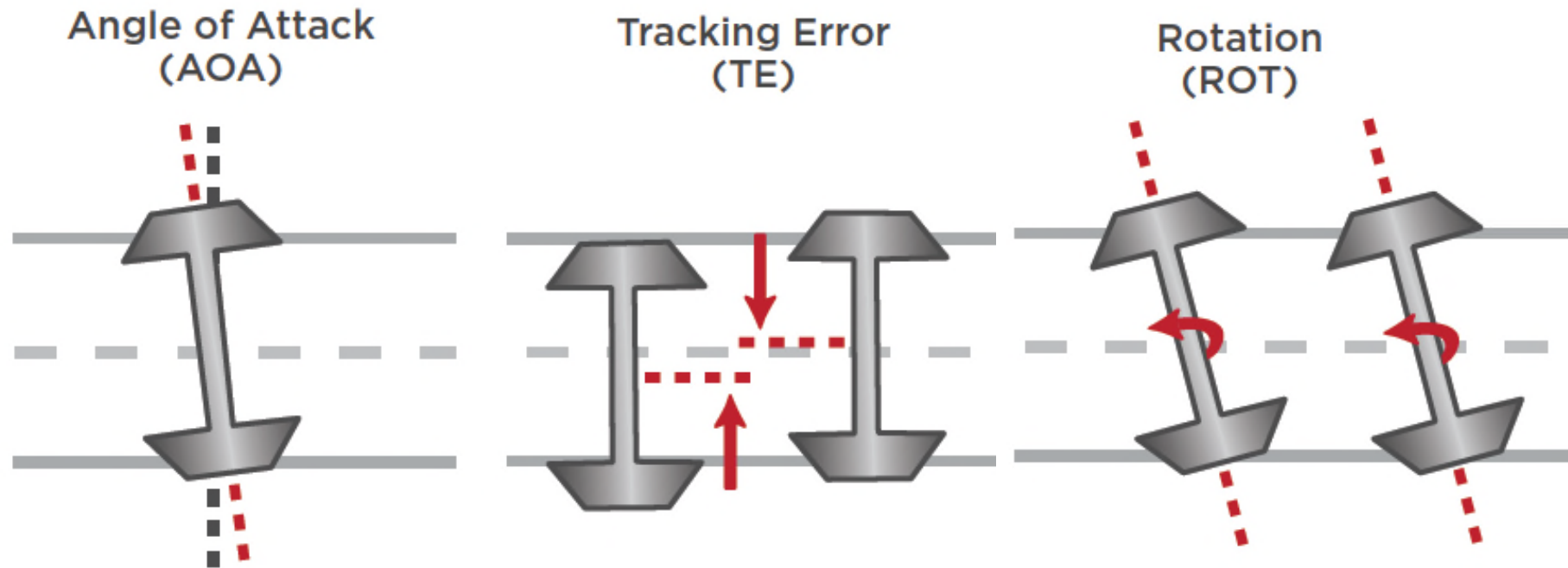


Image from Standard Car and Truck Maintenance Manual  
<http://www.sctco.com/pdf/Section1.pdf>



# How does a truck condition monitor work?



Images from Wayside Inspection Systems  
[http://wid.ca/sites/default/files/brochures/TBOGI/WID\\_TBOGI\\_Brochure\\_US.pdf](http://wid.ca/sites/default/files/brochures/TBOGI/WID_TBOGI_Brochure_US.pdf)



# Impact Measurement





# Wheel Impact Load Detector (WILD)



Image from L.B. Foster  
<https://www.youtube.com/watch?v=7CJycCggHgw>







Image from Frauscher  
<https://www.youtube.com/watch?v=gTfU4tGZzgo>





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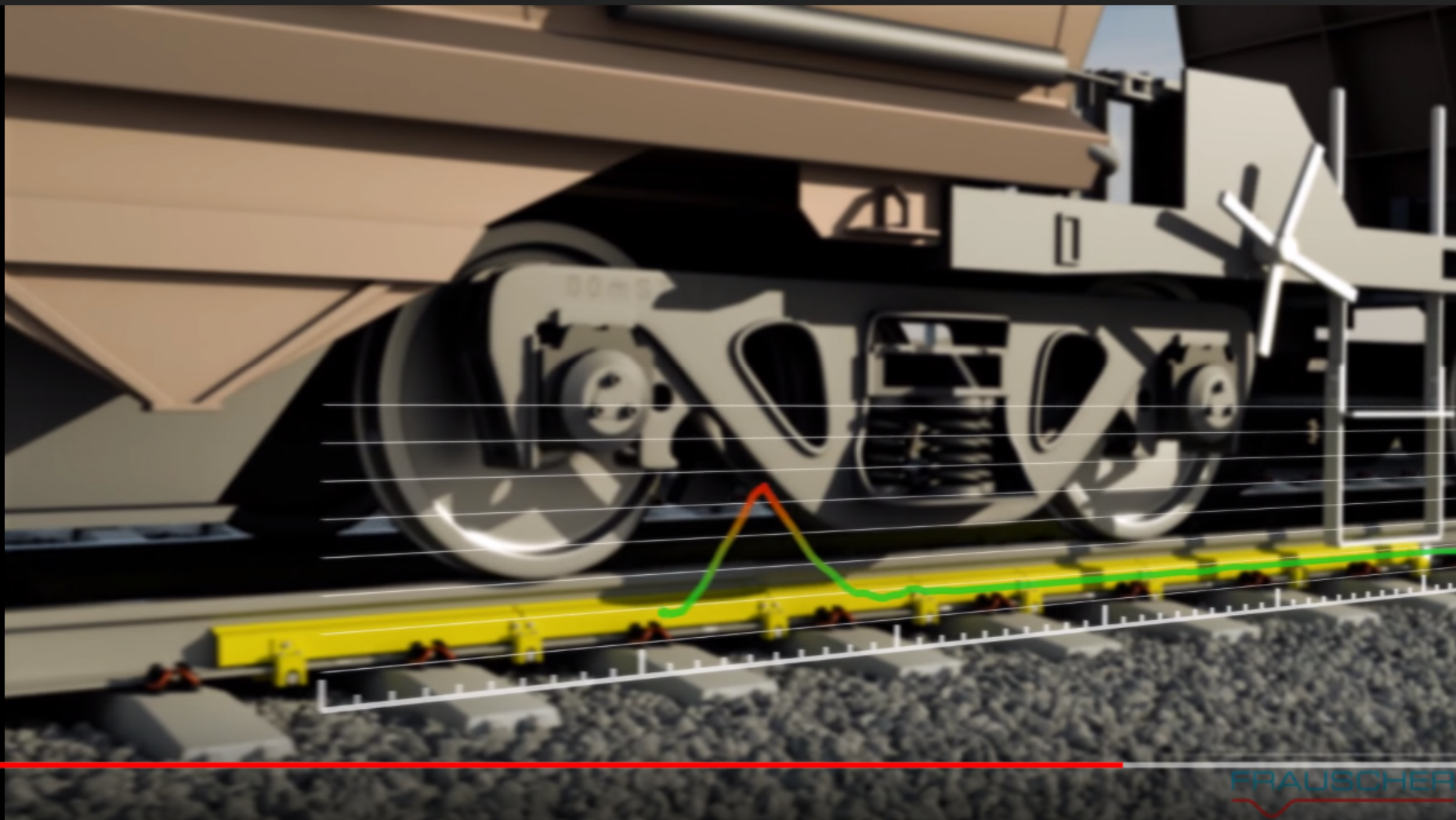


Image from Frauscher  
<https://www.youtube.com/watch?v=gTfU4tGZzgo>





# Example WILD Defects



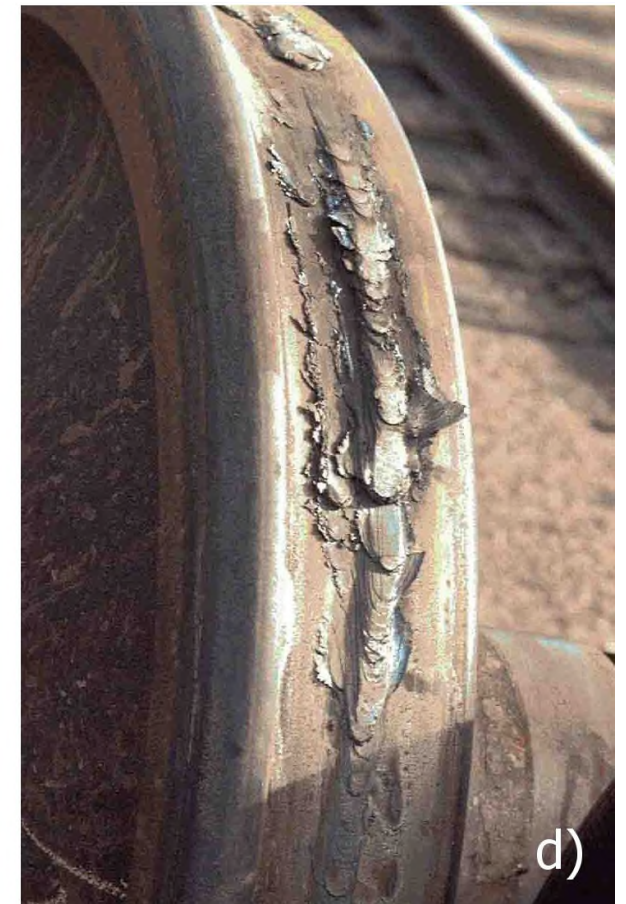
Slid Flat



Shelling & Spalling



Shattered Rim



Built Up Tread



## Measurements

- Nominal Load
- Peak Load
- Dynamic Load (=Peak-Nominal)
- Ratio (=Peak/Nominal)

## Things to Keep in Mind

- Loaded/Empty
- Speed
- Track Stiffness





# V/TI Monitor – Impact Measurement



Example V/TI Monitor Axle Sensor



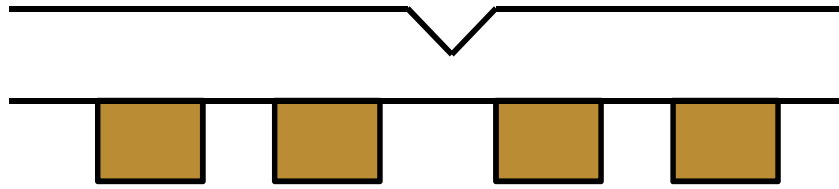


# Vehicle Platforms: Revenue Vehicles

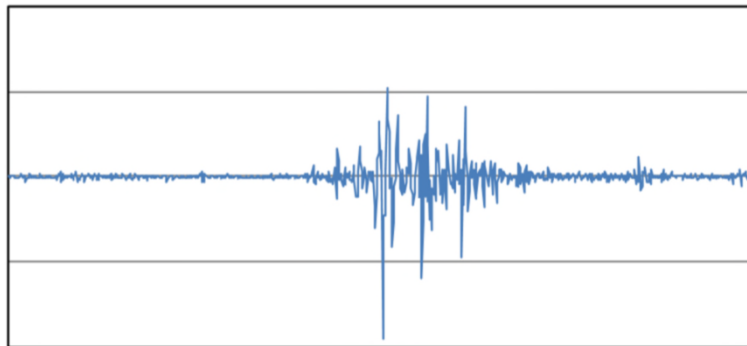
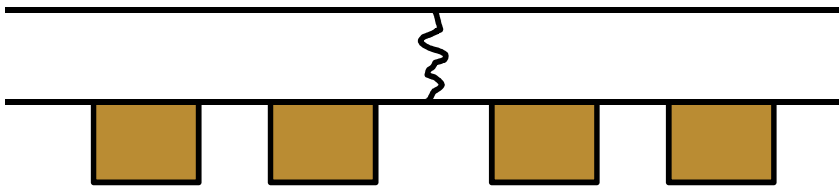




Dent



Break



- Vertical acceleration measured at axle box
- Wheel/Rail Impact acceleration measured
- Peak acceleration is used to calculate peak load.



# Example V/TI Monitor Defects



Battered Joint



Cracked/Broken Joint Bar



Cracked/Broken Frog



Broken Rail



# Measurements

- Peak Load

# Things to Keep in Mind

- Loaded/Empty
- Speed
- Track Stiffness



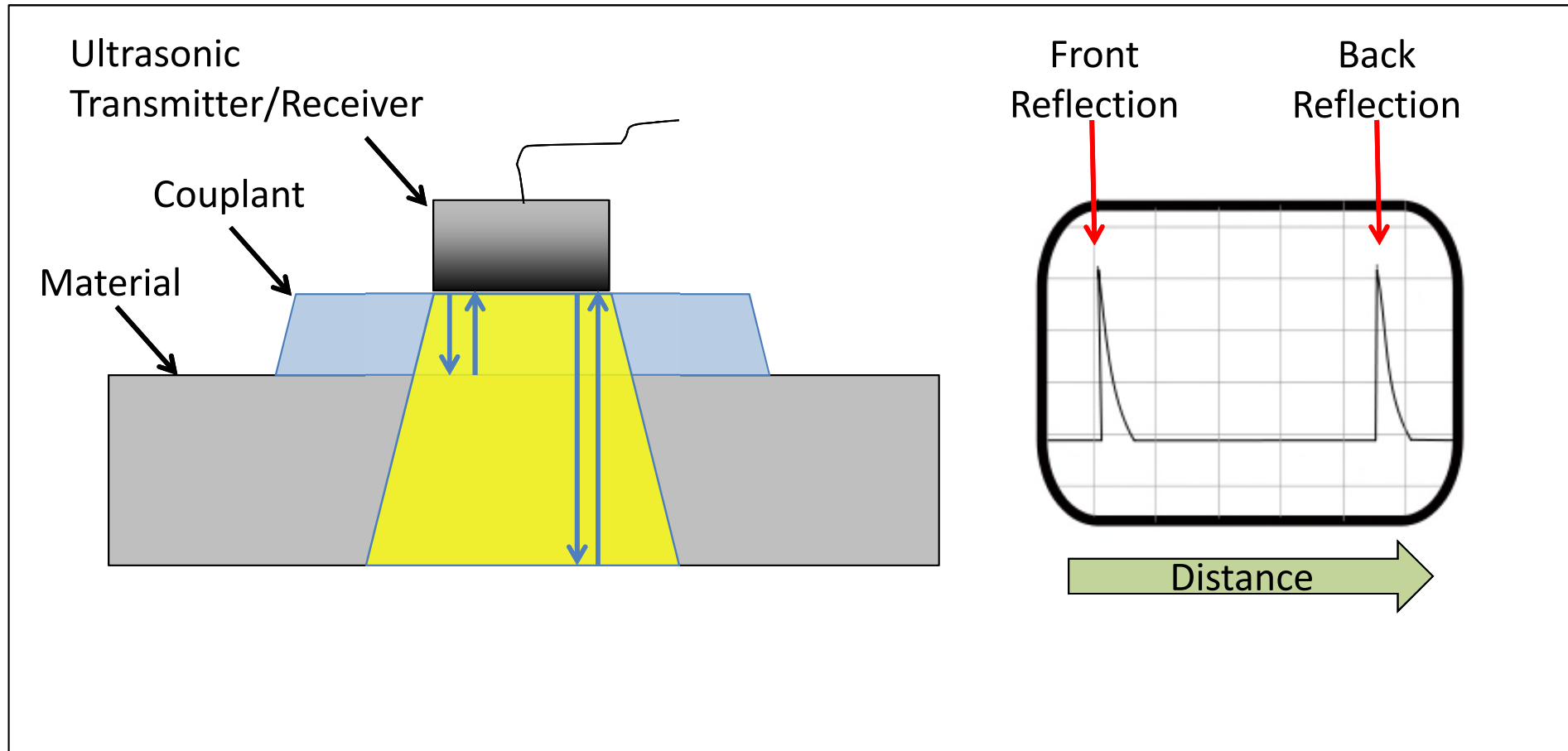
# Ultrasonic Measurement





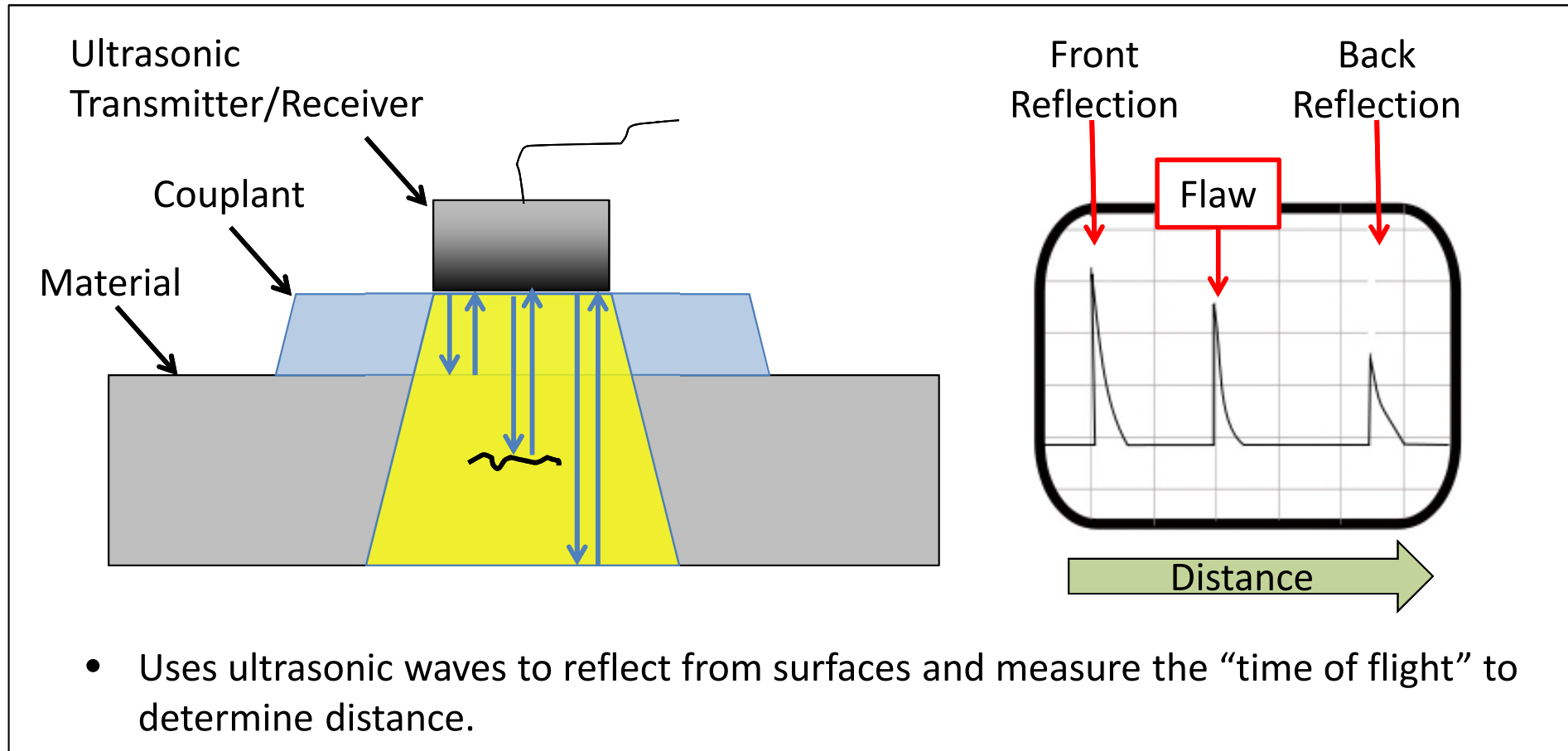
# Ultrasonic Sensors

- Can measure depth, size, and orientation of internal flaws in a material



# Ultrasonic Sensors

- Can measure depth, size, and orientation of internal flaws in a material



# Ultrasonic Rail Flaw Detectors

Example Wheel Probe System  
(Most Commonly Used in North America)

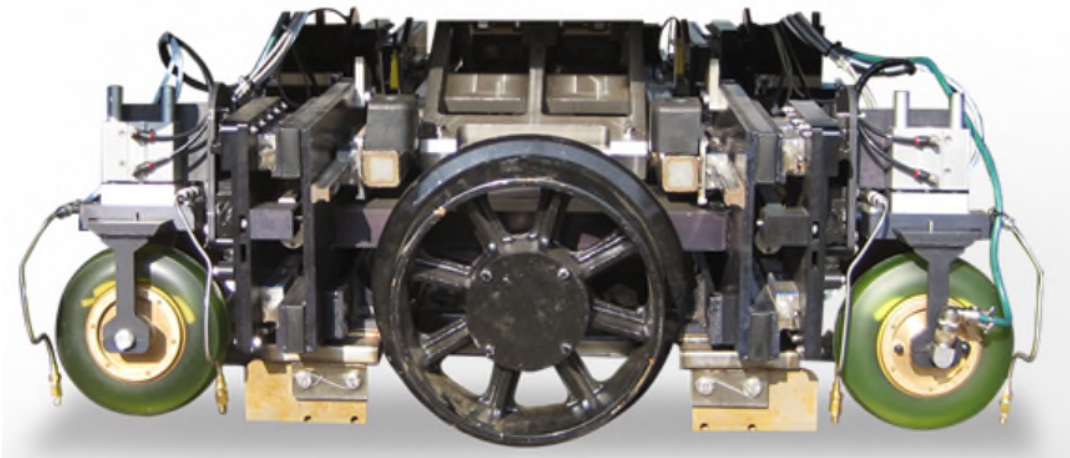
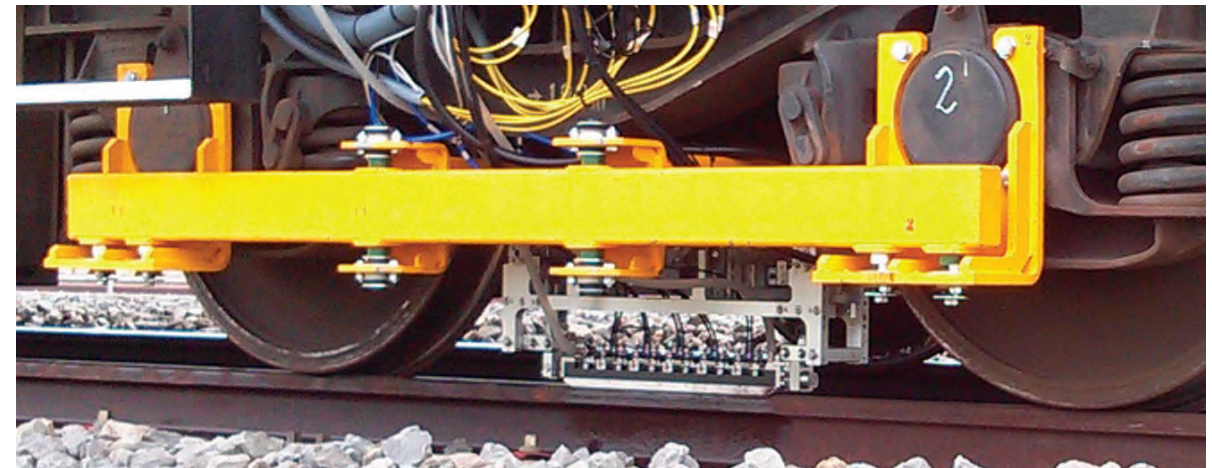


Image from Nordco  
<http://www.nordco.com/products-catalog/inspection-technologies/rail-bound-inspection-systems/rail-bound-rail-flaw-inspection-system-.htm>

Example Sled Probe System  
(Most Commonly Used in Europe)



ScanMaster  
<http://scanmaster-irt.com/wp-content/uploads/2015/11/TrackMaster-High-Speed-brochure.pdf>





# Vehicle Platforms:



Railbound Manned



Hi-Rail Manned



ATV Manned



## B-Scan



Composite of multiple sensors to better visualize the flaw

## A-Scan



Individual Sensor



Image from Nordco  
<http://www.nordco.com/products-catalog/inspection-technologies/vehicle-inspection-systems/NRS-260-Prime.htm>





# Cracked Wheel Detector



Image from Proceedings of 2018 AAR Review Matthew Witte, "Effectiveness of Cracked Rim Detectors to Identify Broken Wheels"





# Example Plunger Probe System

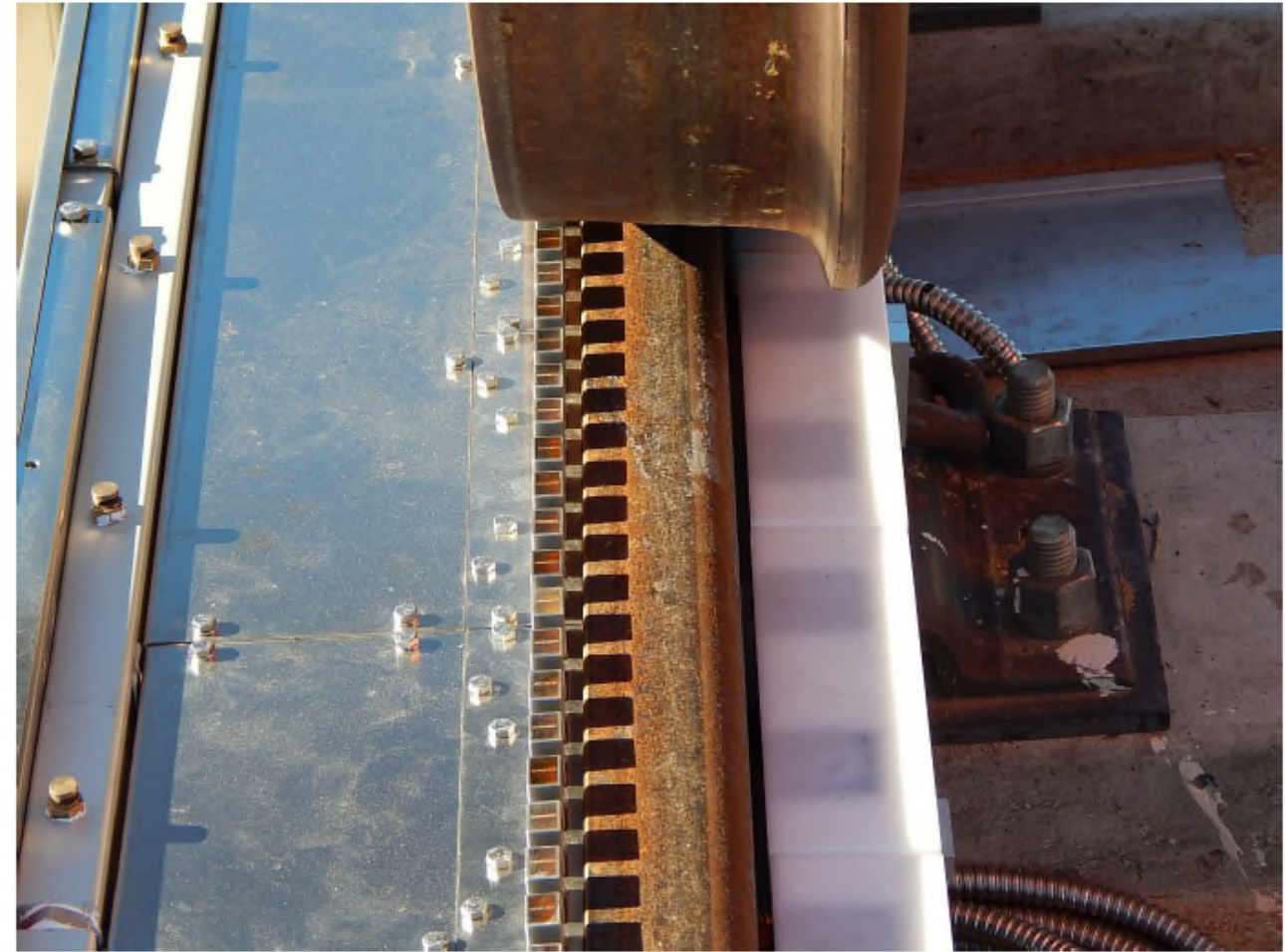


Image from Proceedings of 2018 AAR Review Matthew Witte, "Effectiveness of Cracked Rim Detectors to Identify Broken Wheels"





# Example Robotic System

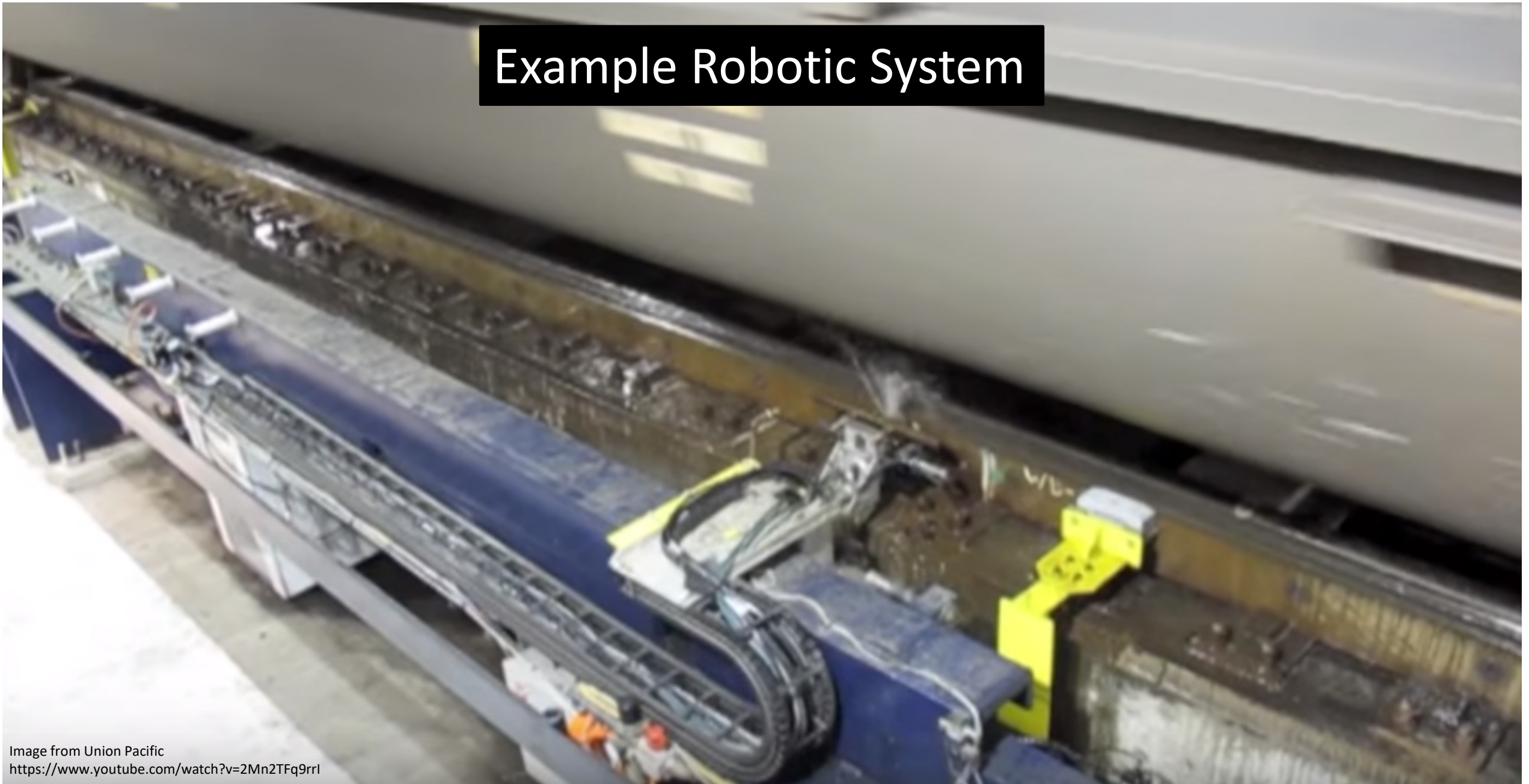


Image from Union Pacific  
<https://www.youtube.com/watch?v=2Mn2TFq9rrl>



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**WRI 2019**

# Example Robotic System

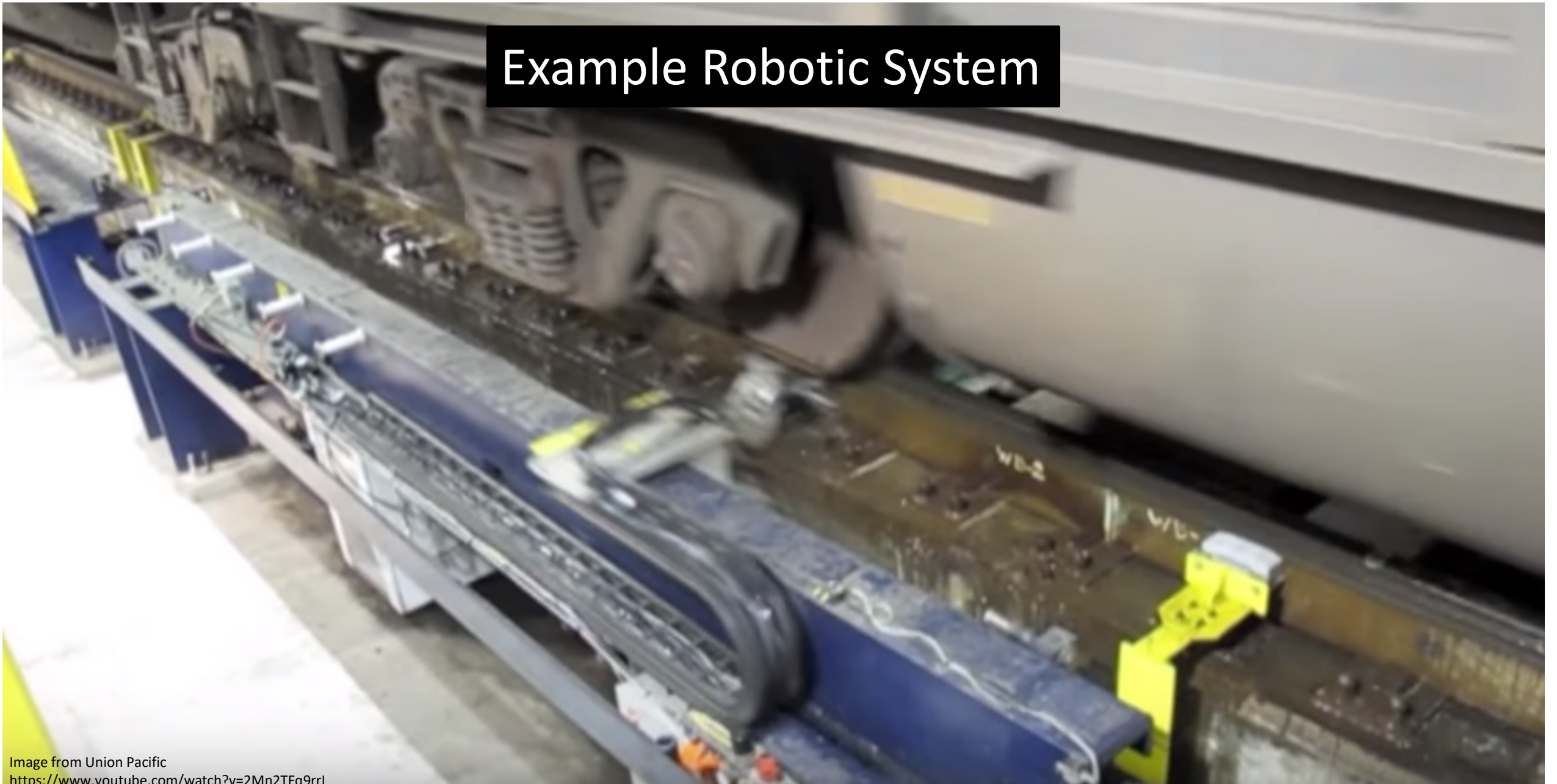


Image from Union Pacific  
<https://www.youtube.com/watch?v=2Mn2TFq9rrl>





# Imaging



# Cameras

## “Line Scan” Cameras aka “Slit Scan”

Works like your document scanner

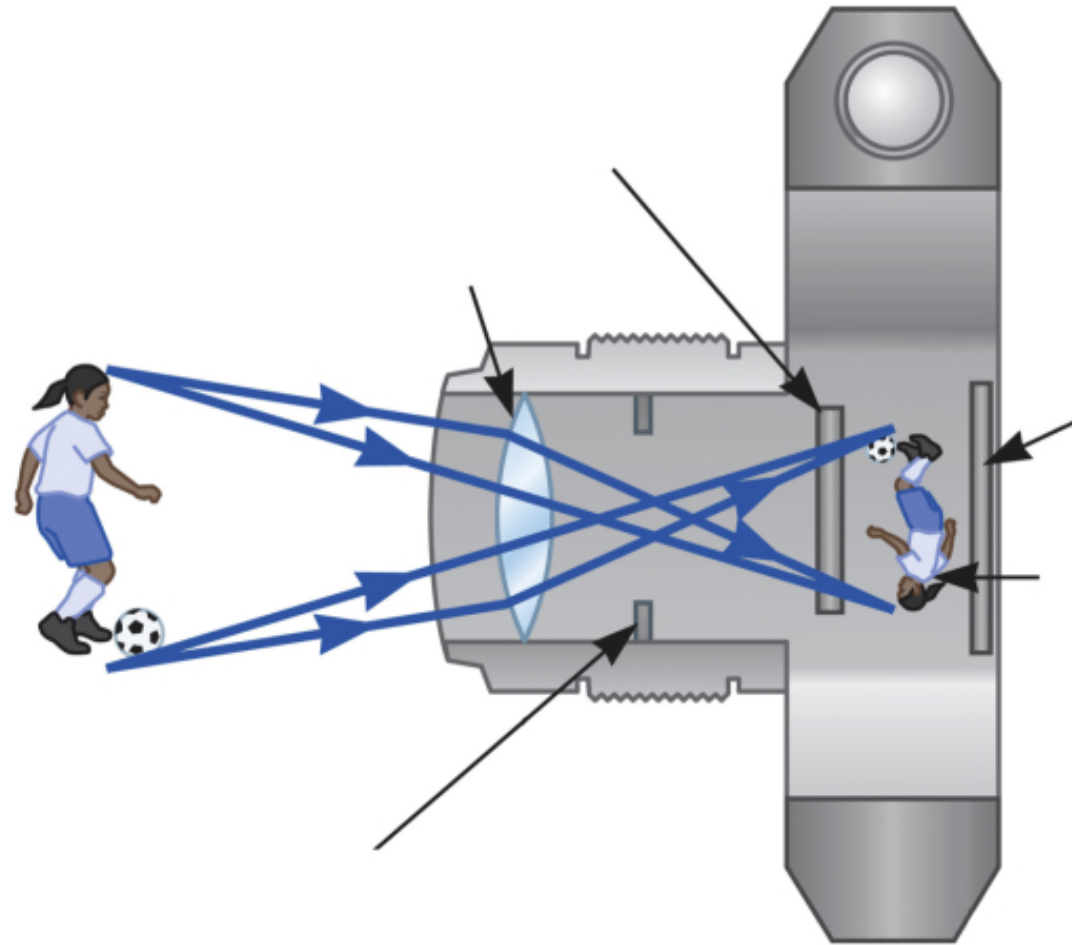


## “Area Scan” Cameras aka “Full Frame”

Works like your standard camera



# Cameras

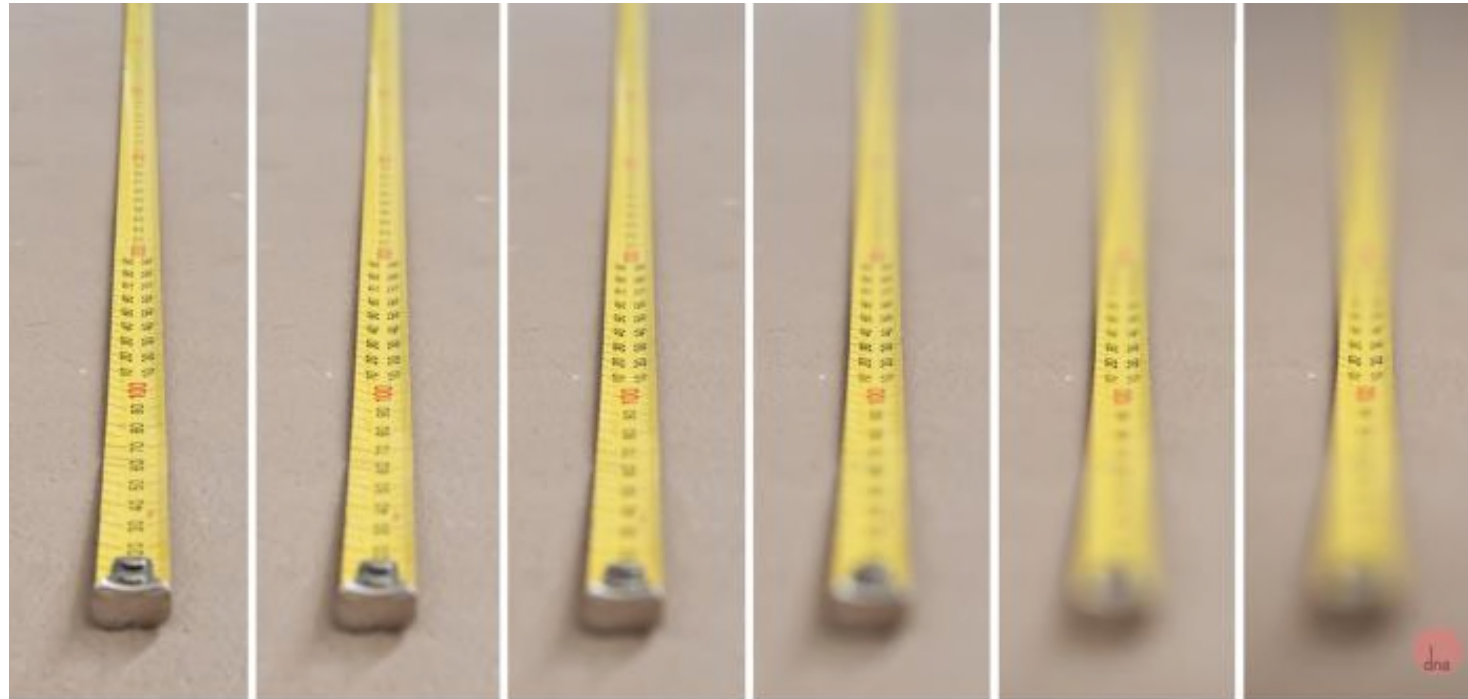


Ref: <http://www.physics.byu.edu/faculty/colton/courses/phy123-fall12/warmups/jitt30a.html>





# Cameras



F16



F10



F6.3



F3.5



F2



F1.4

Ref: <https://www.ormsdirect.co.za/blog/2012/05/08/what-is-aperture-desmond-louw-explains/>



# Cameras

*What is needed for a railroad application:*

Ideally want **large depth of field (small aperture)** for maximum content in focus.

Want **fast shutter speed** to capture quickly moving objects.

Generally **need lots of light.**



# Example Camera Systems



Wheel Sensor

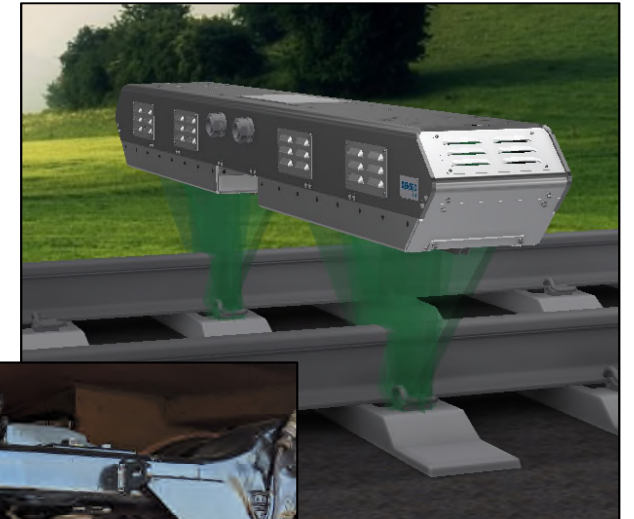




# Example Camera Systems



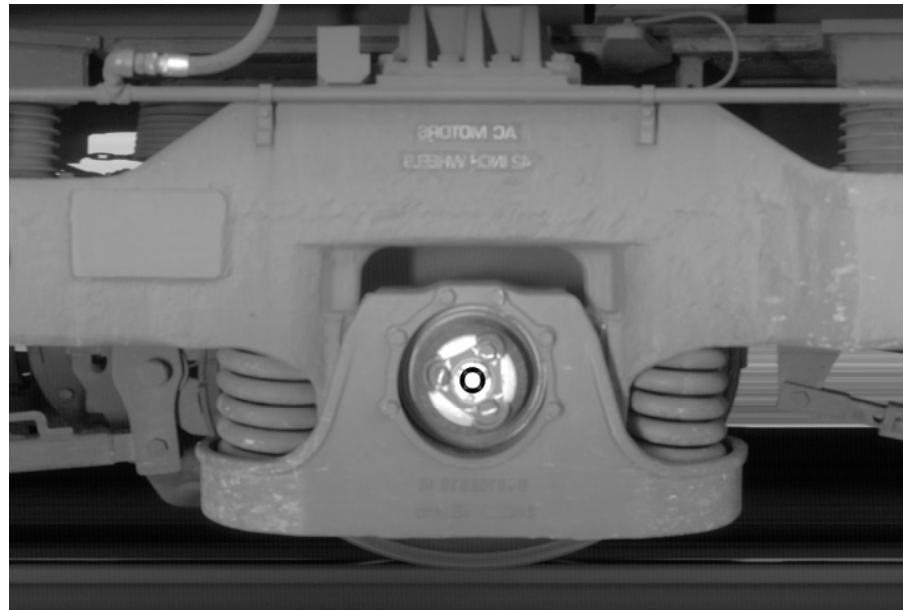
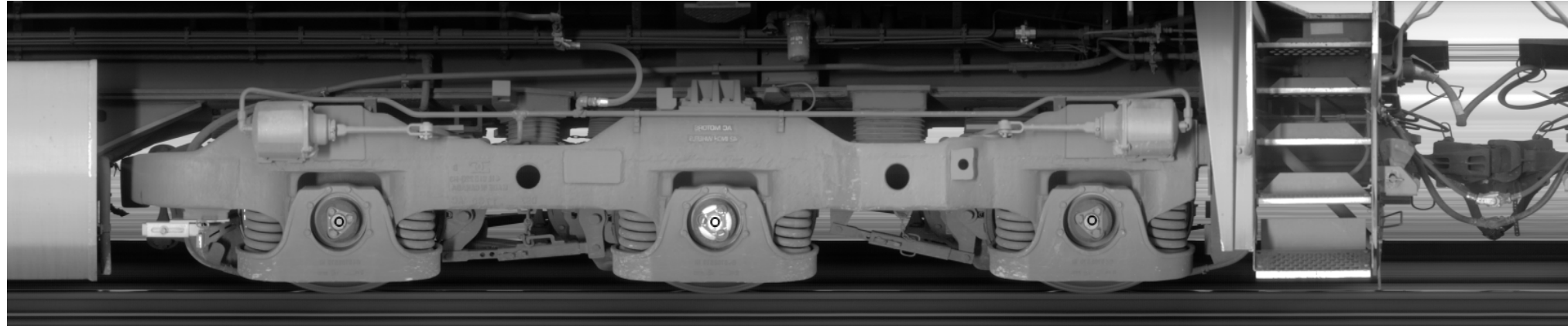
Track Component Imaging



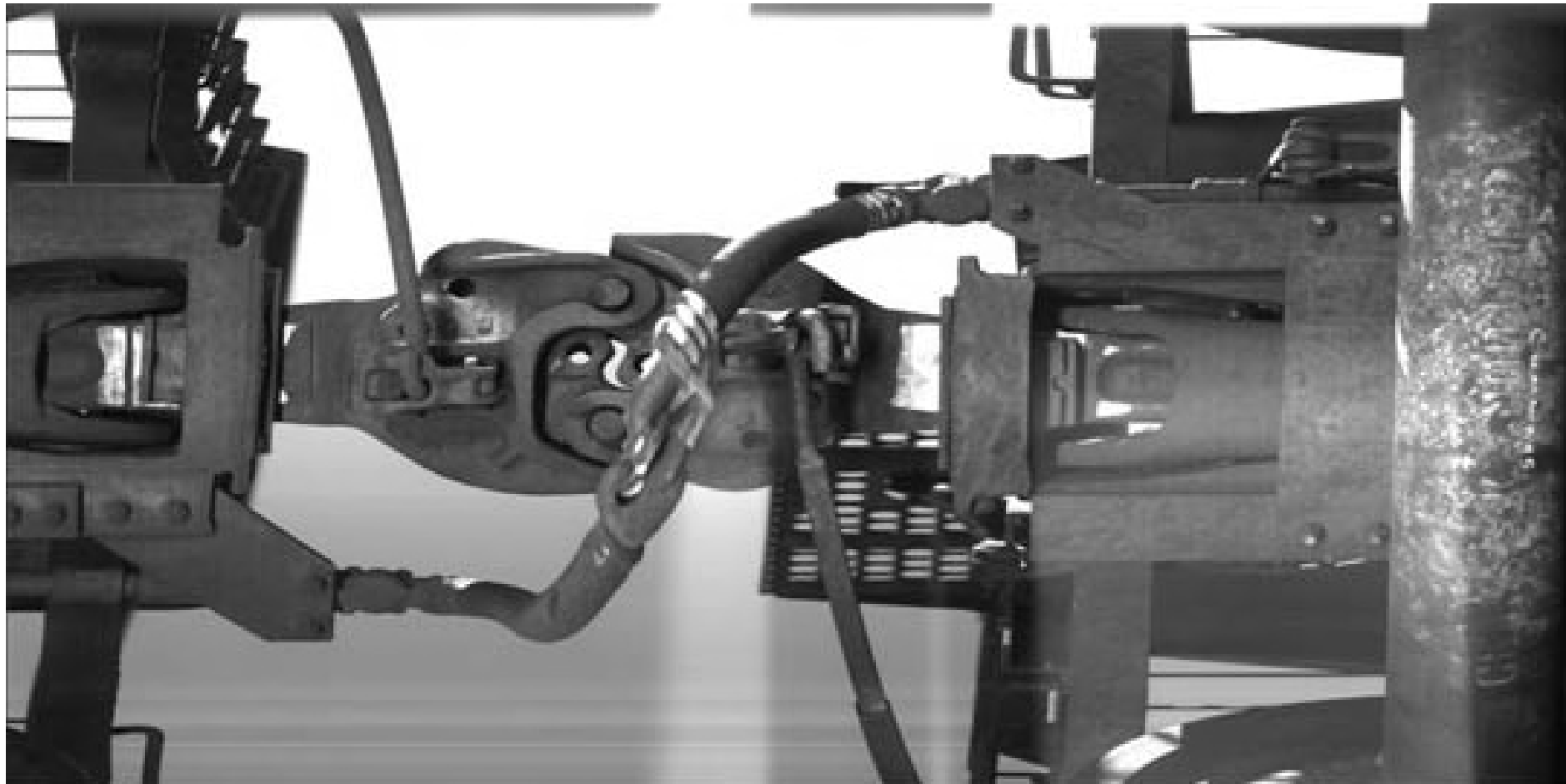
Joint Bar Imaging



# Example Line Scan Images



# Example Line Scan Images

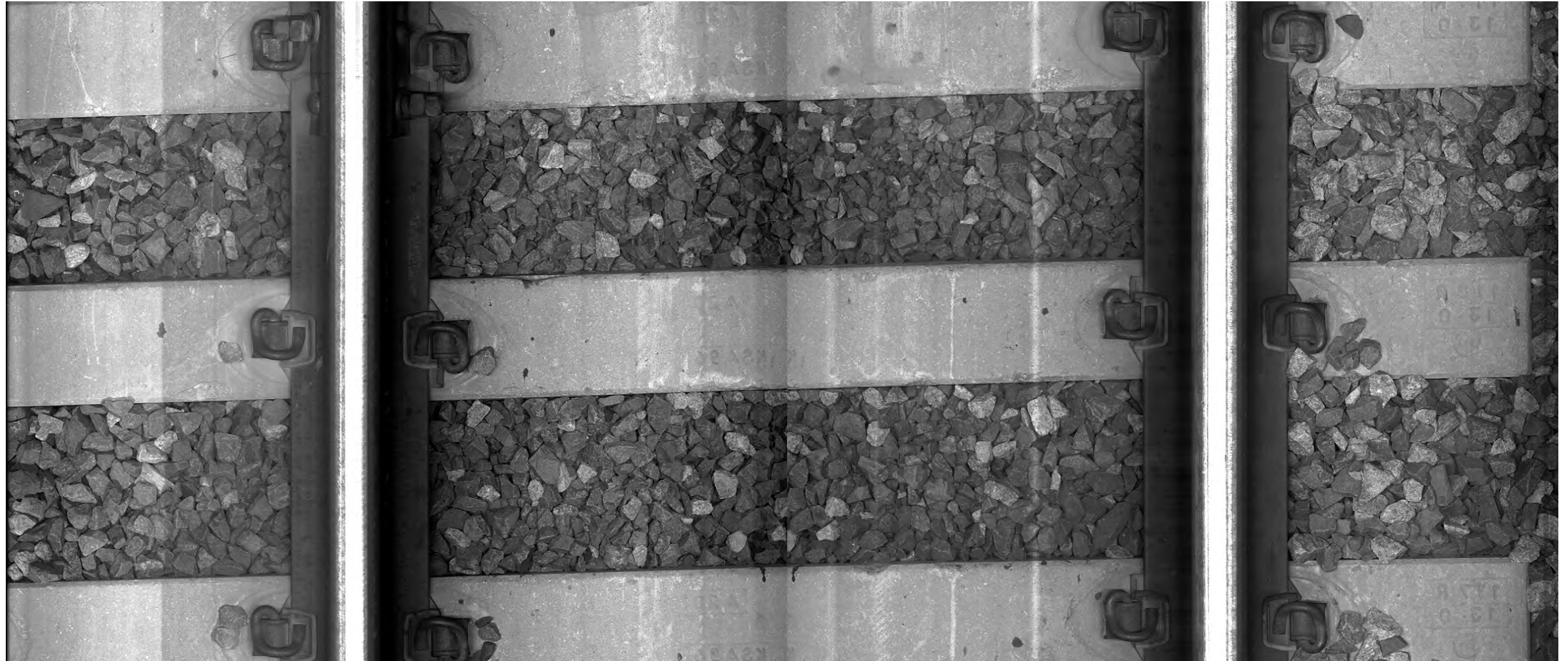




# Example Line Scan Images

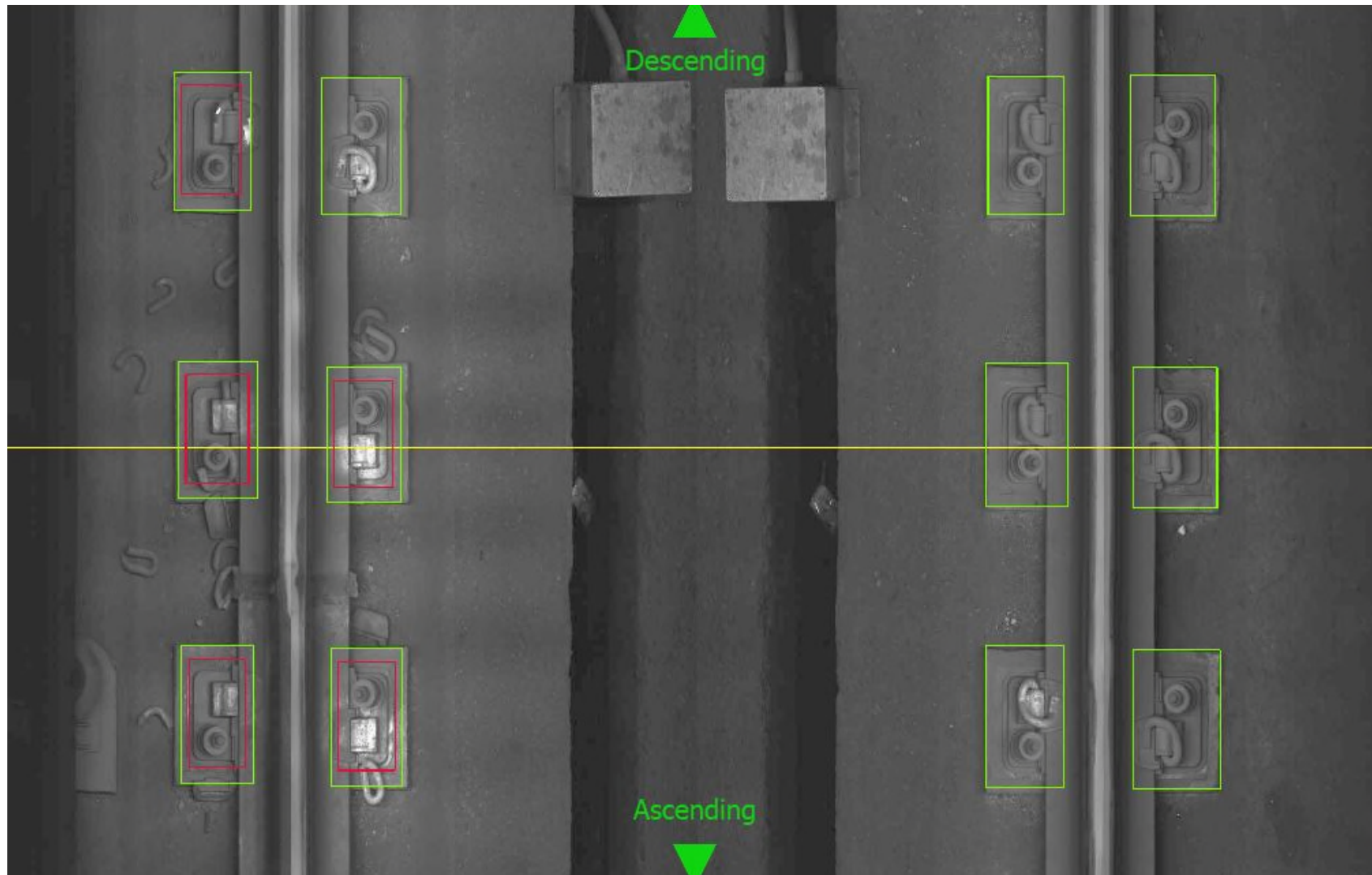


# Example Line Scan Images





# Example Automated Exception Detection using Line Scan Images





# Example Automated Strip Chart Generation using Line Scan Images

Curvature (deg)

Crosslevel (in)

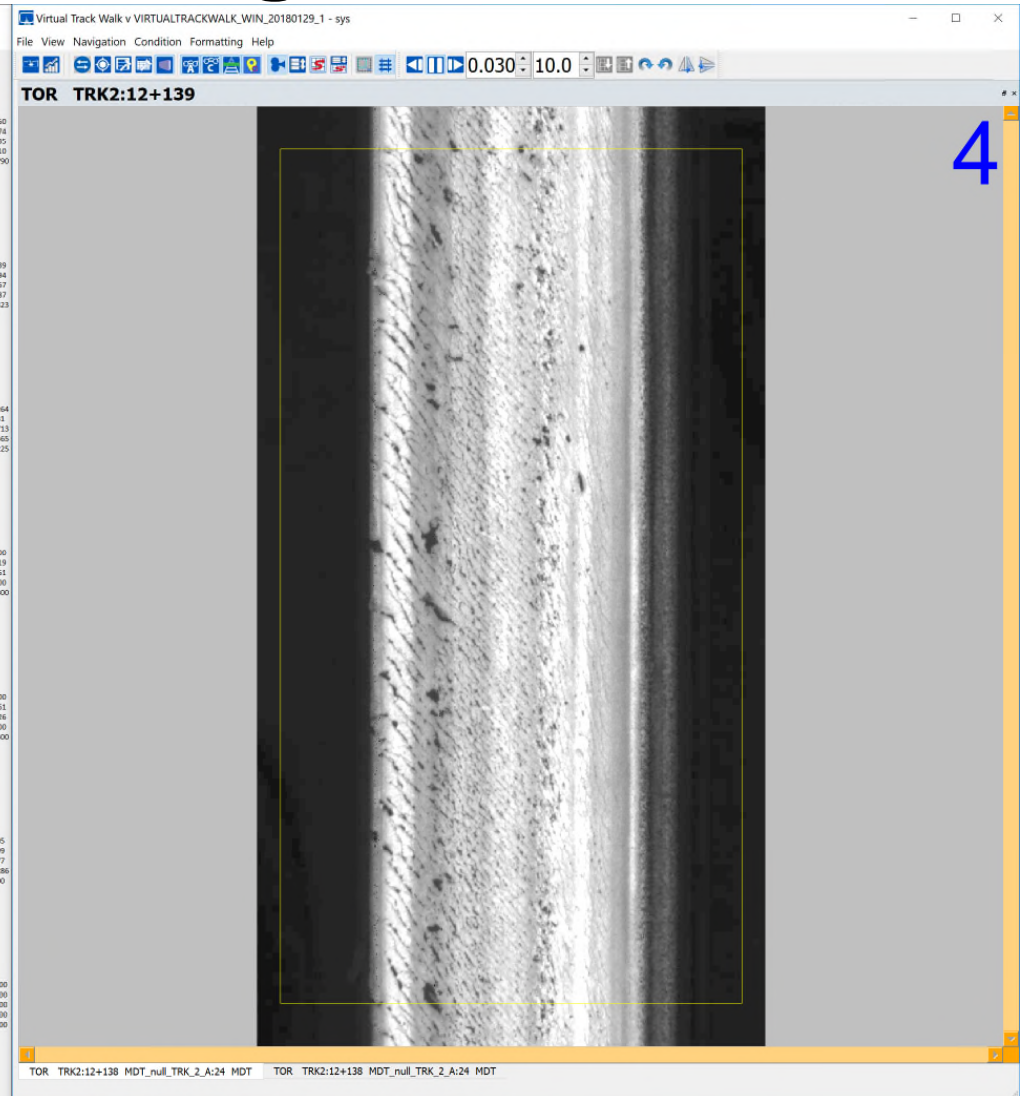
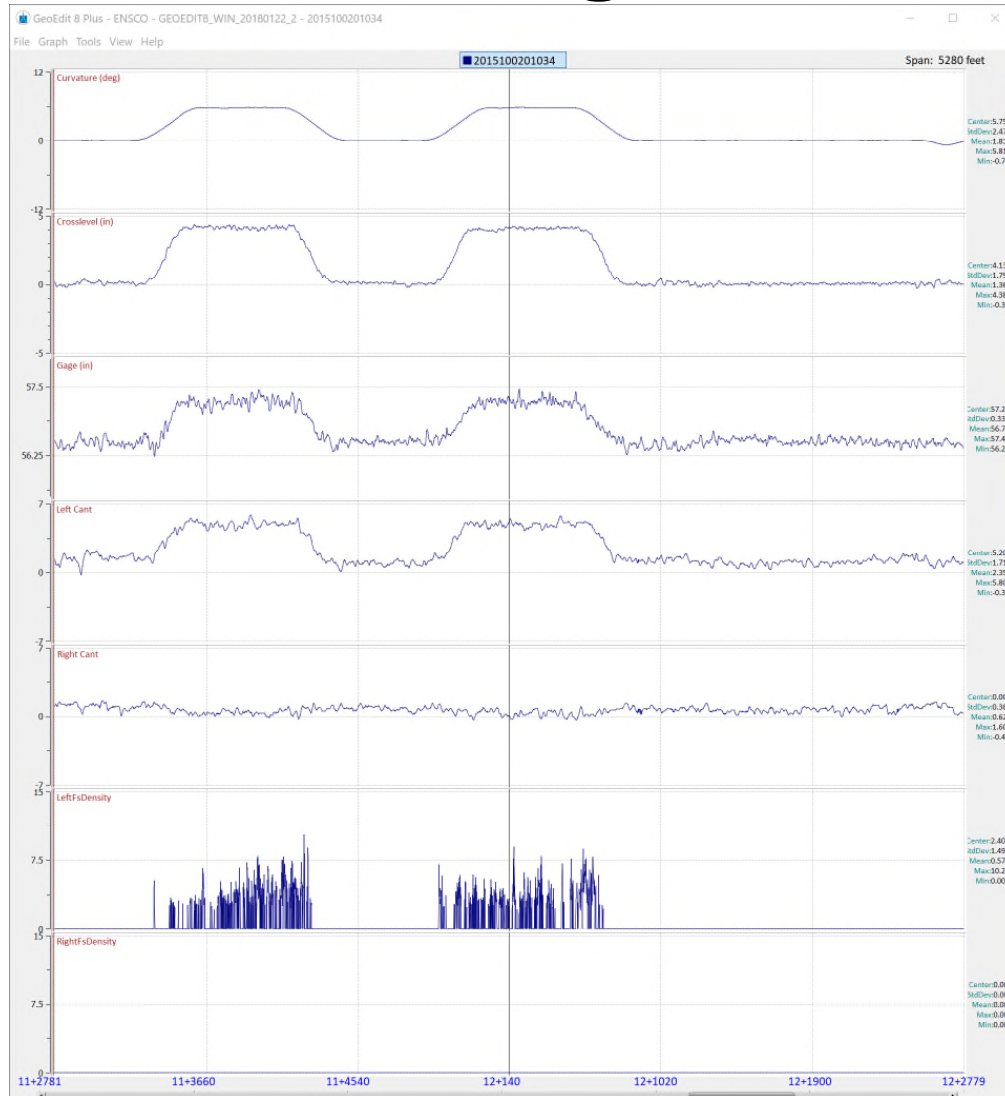
Gage (in)

L Cant (deg)

R Cant (deg)

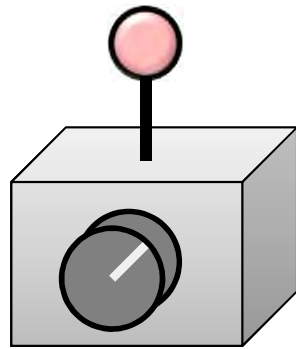
L FS Crack Density

R FS Crack Density



# Asset Management

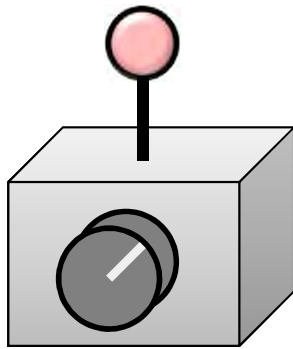




System identifies problem when measurement **exceeds threshold** and transmits direct to field personnel for repair.

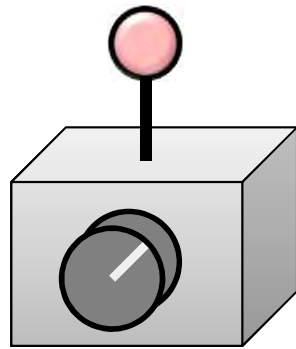






I want to know this ahead of time to plan better!





# Asset Management



Data Validation  
& Correction



Asset  
Assignment



Prediction & Work  
Identification



Resource  
Planning







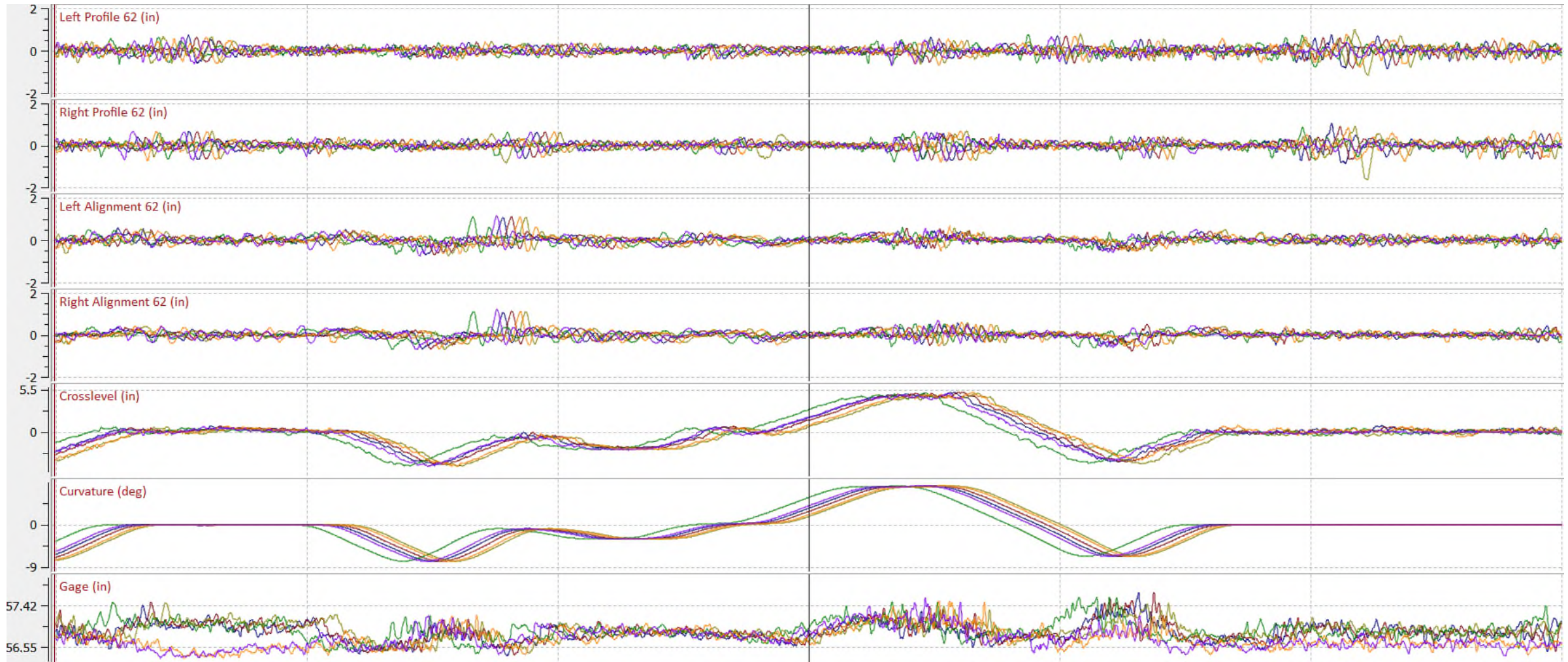
## Data Validation & Correction

- We're using measurement like we haven't before.
- This requires a greater need for data accuracy!
  - Erroneous Data Removed
  - Profile Template Matching
  - Data Alignment





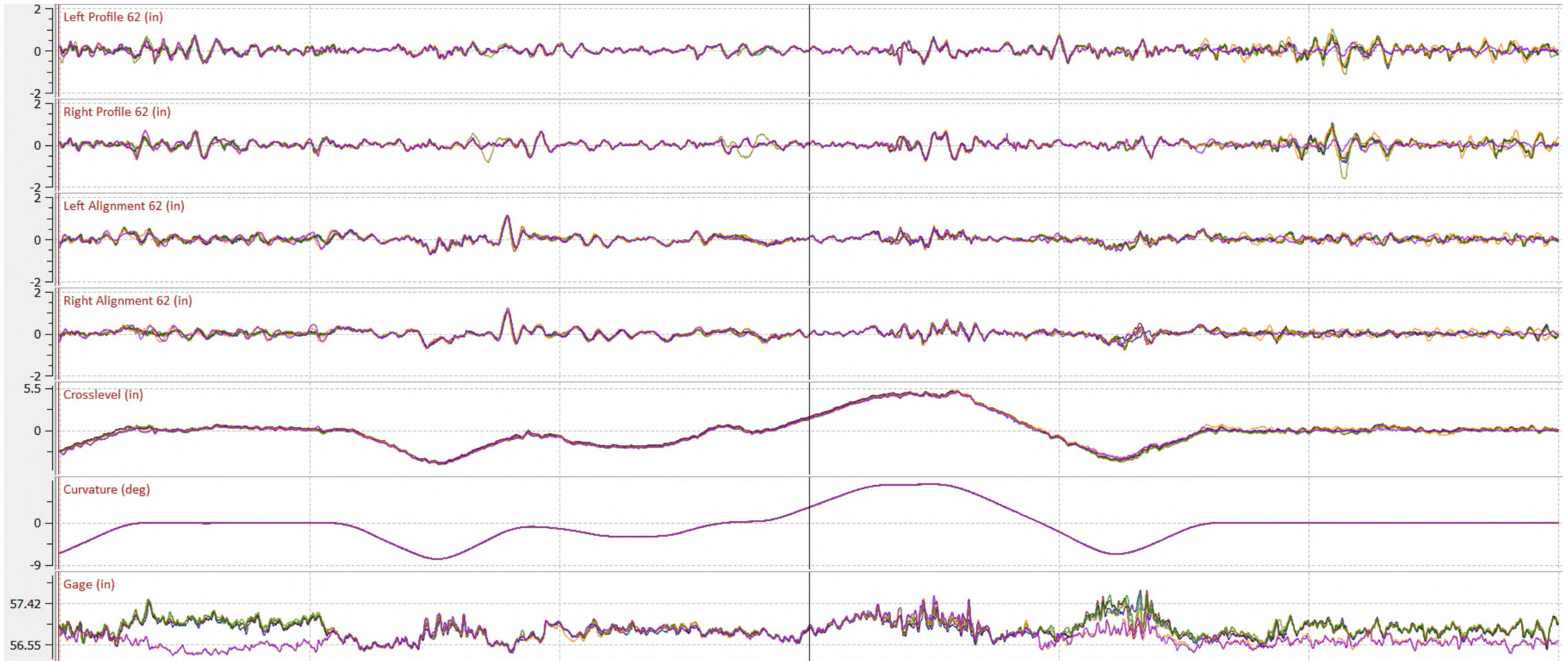
# Data Validation & Correction







# Data Validation & Correction

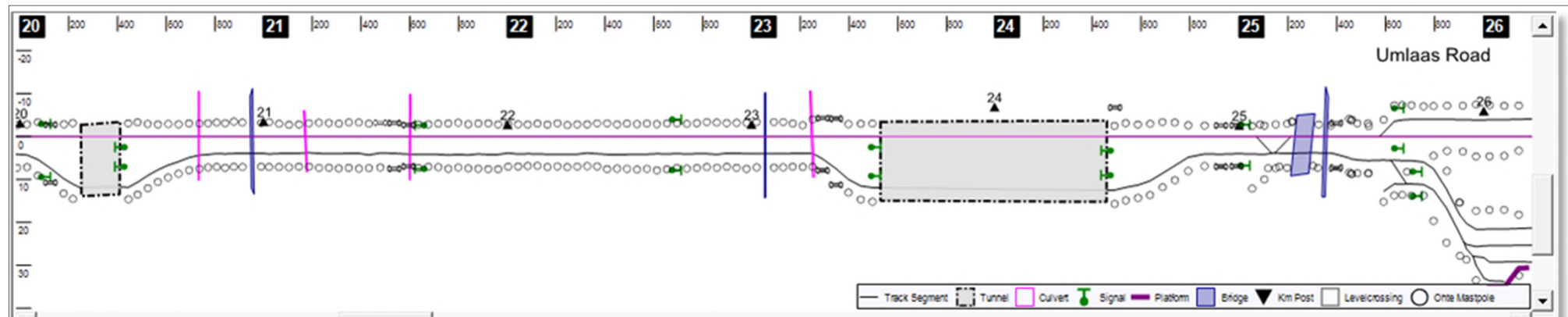






## Asset Assignment

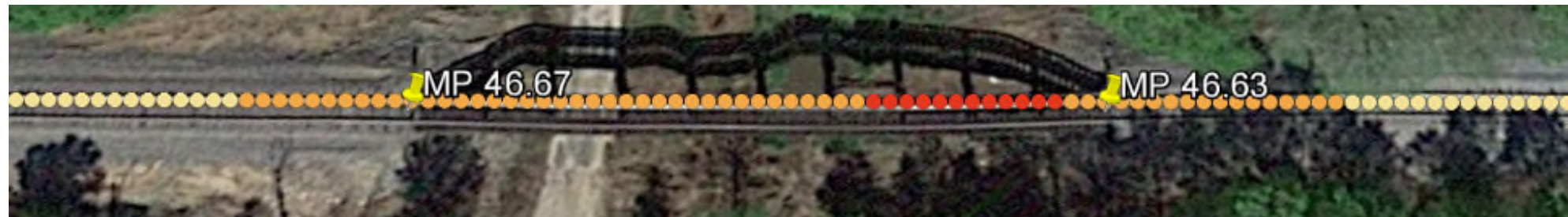
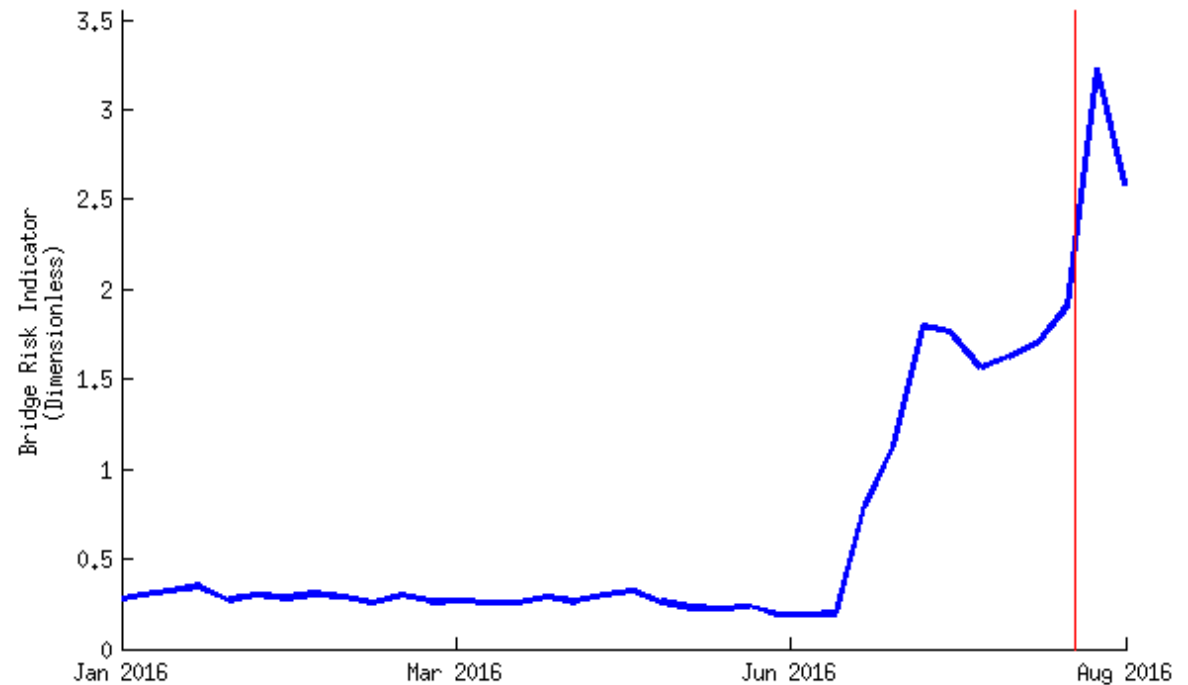
- First: What and where are your assets?
- Second: Assign data to the correct asset.





## Prediction & Work Identification

- If #1 and #2 are done well, #3 is much easier!
- Prediction needs to be prescriptive as much as possible



# 4

## Resource Planning

- Receive the Identified Work associated to Assets.
- Execute the Work with Work Orders.
- Linear Asset Management (LAM)

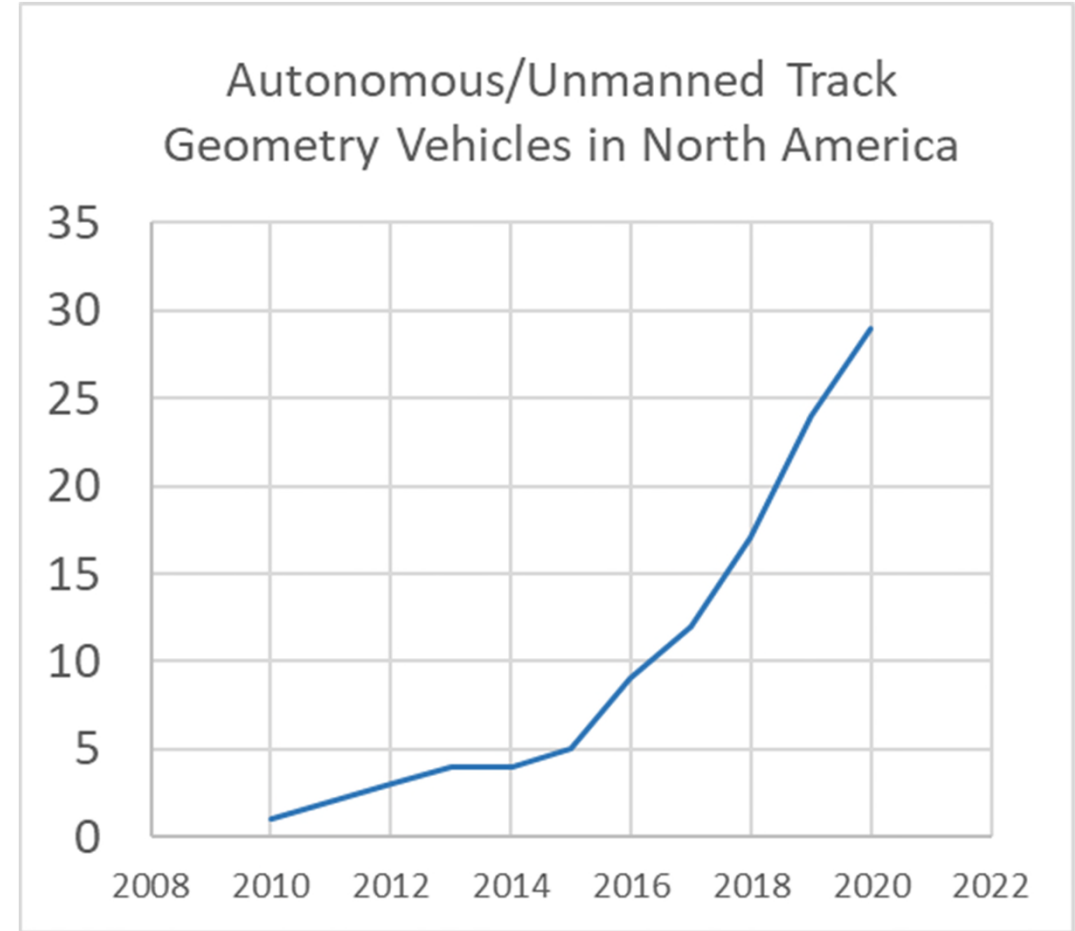
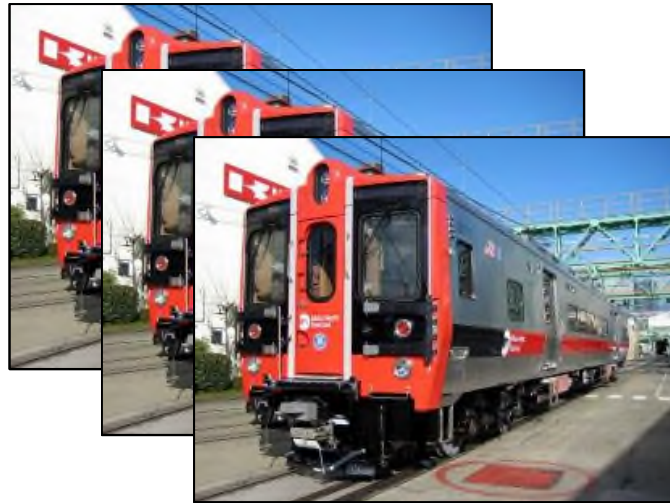




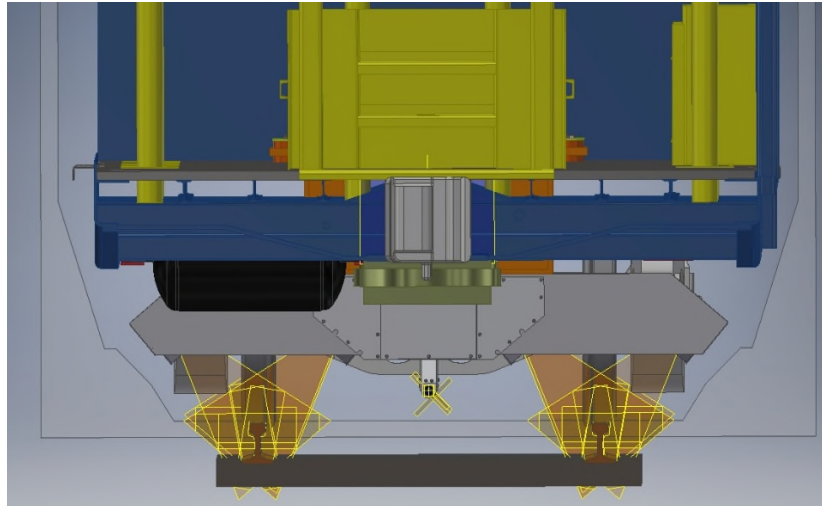
# The Future is Here



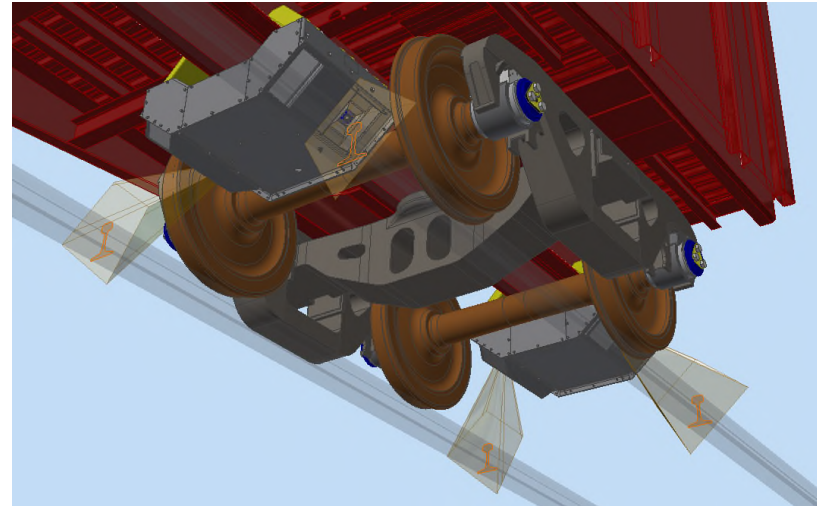
# 1) Autonomous Track Inspection



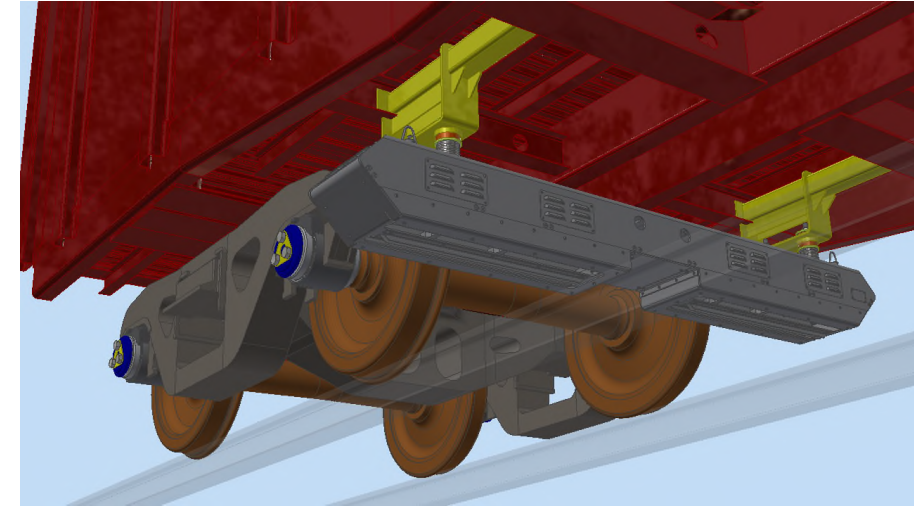
# 1) Autonomous Track Inspection



**Carbody  
Mounted  
Autonomous  
Rail Profile**



**Carbody  
Mounted  
Autonomous  
Zero Speed  
Track Geometry**



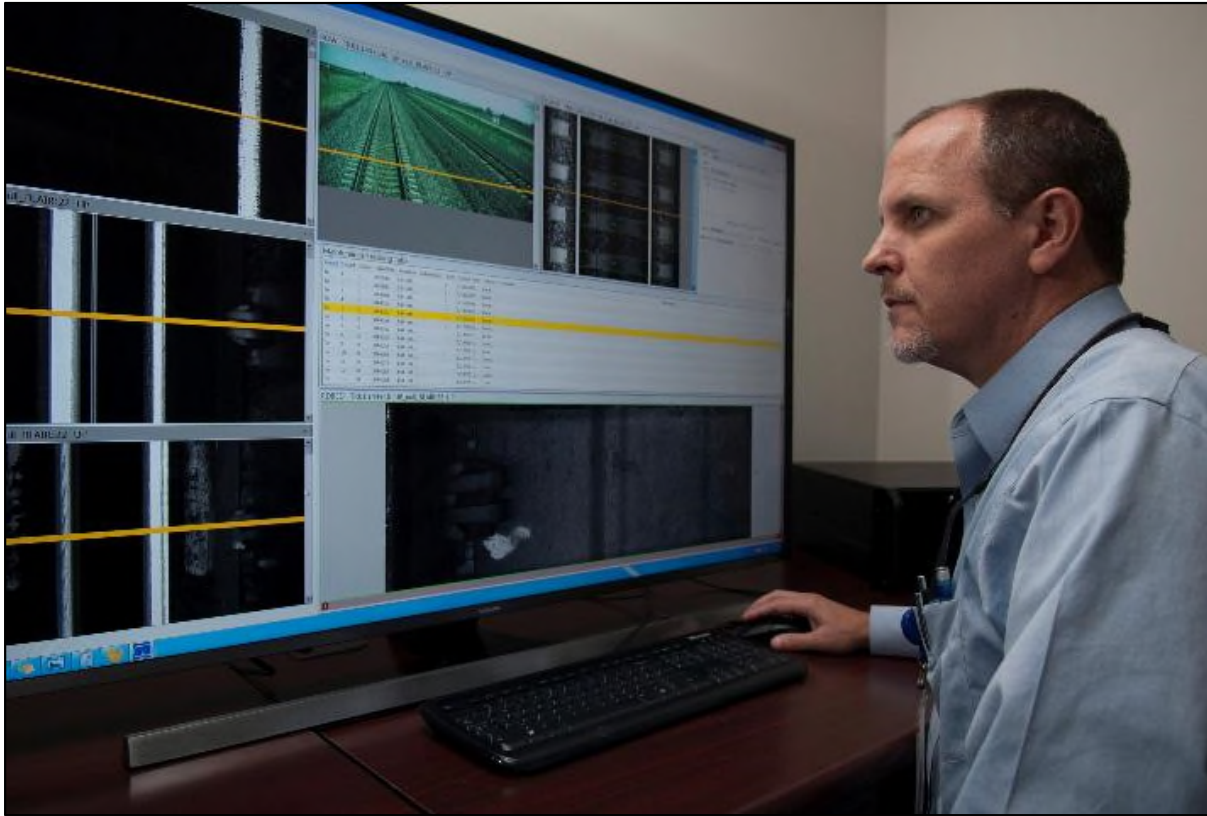
**Carbody  
Mounted  
Autonomous  
Joint Bar  
Imaging**





# 2) Field Inspections in the Office

## Track Inspection



## Train Inspection



Ref: <https://beenavision.com/TrainWatch.php>



# Questions?

